HEC-RAS Mapper Results Visualization

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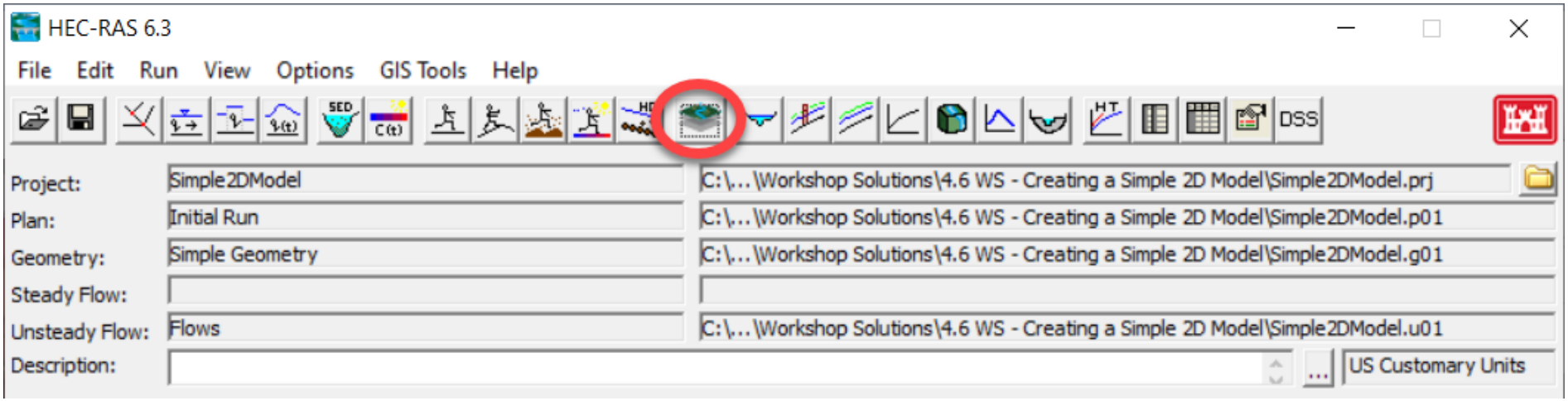
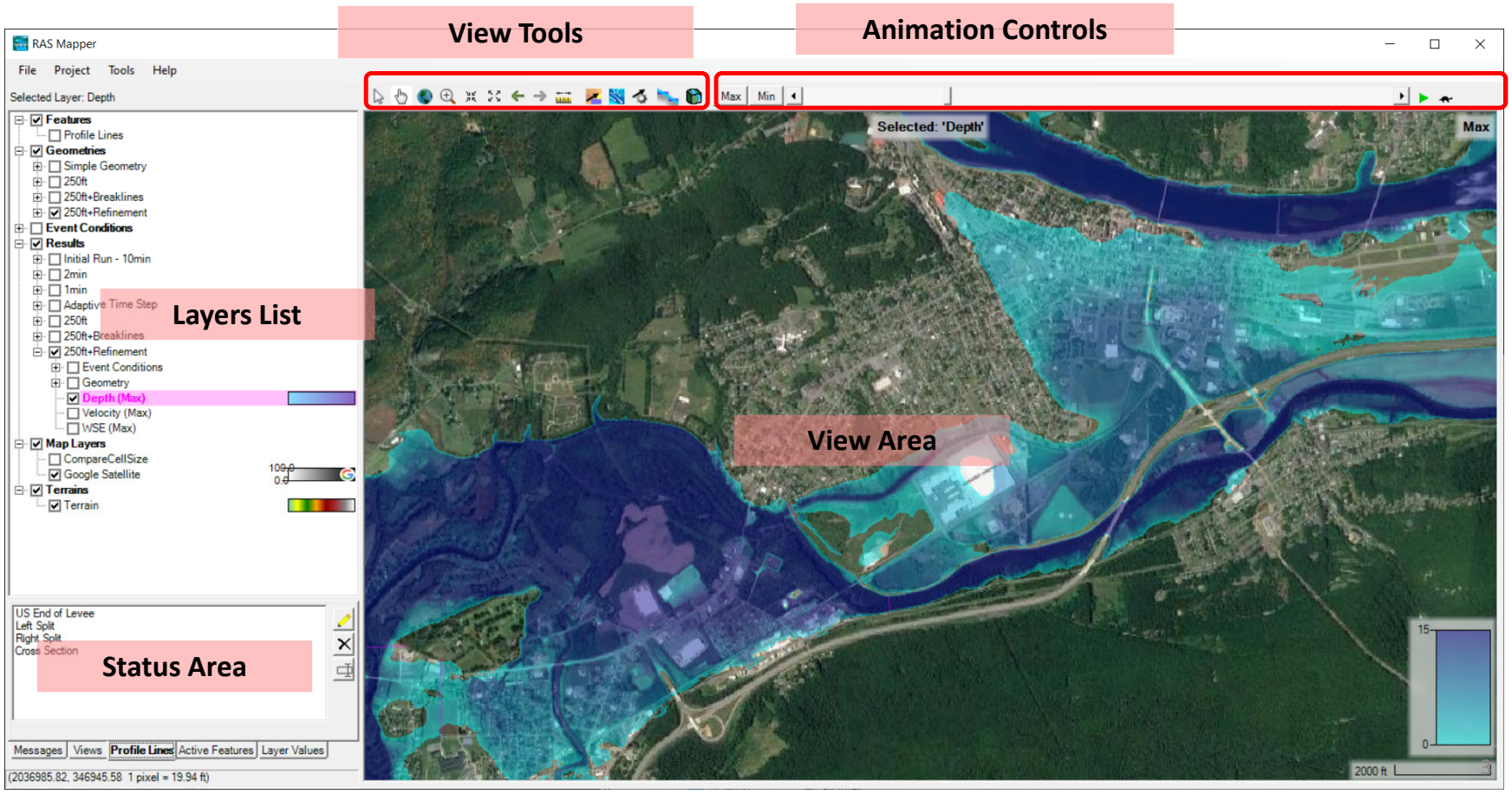
US Army Corps of Engineers

Overview

- How do we visualize RAS results?
- How do we debug our model?
- How do we compare different plans?

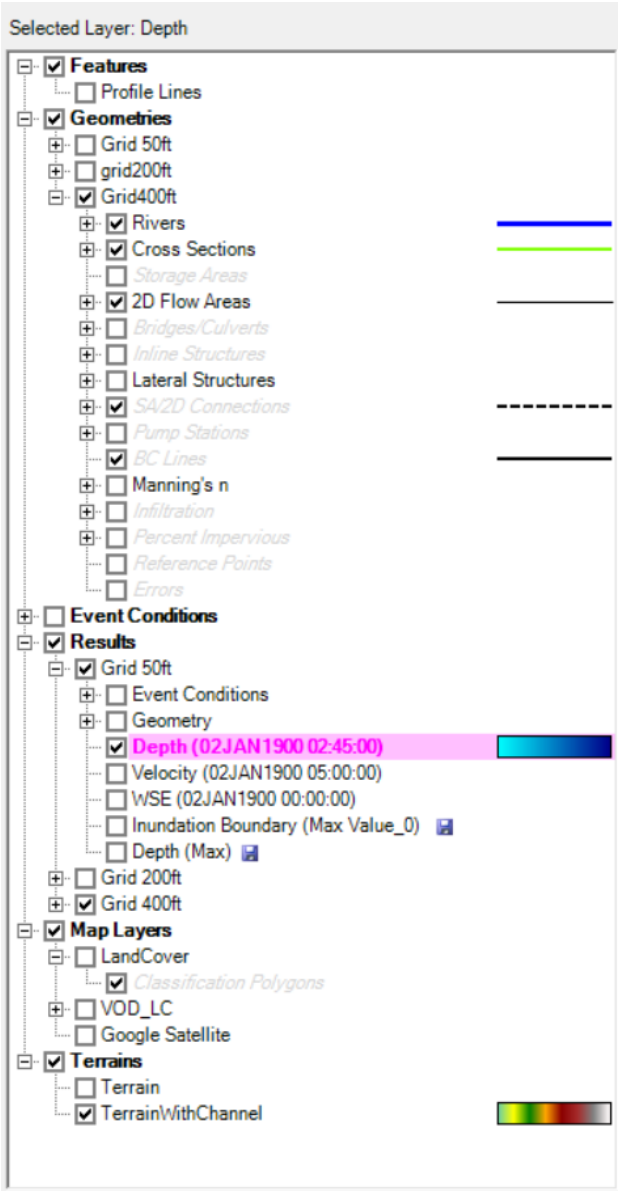


HEC-RAS Mapper



Layers List

- Profile Lines
- Geometries
- Results
- Map Layers
- Terrains

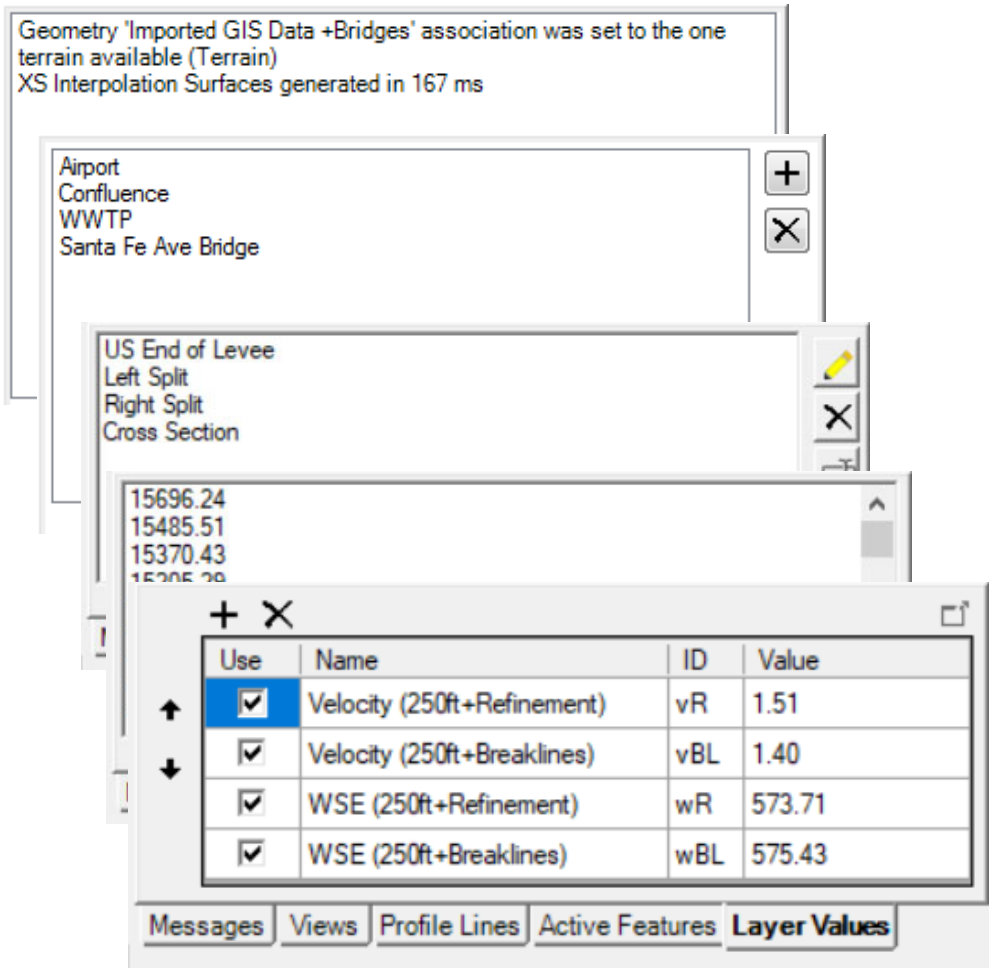


Symbology is shown to the right of any checked layers.

The selected layer is highlighted in magenta.

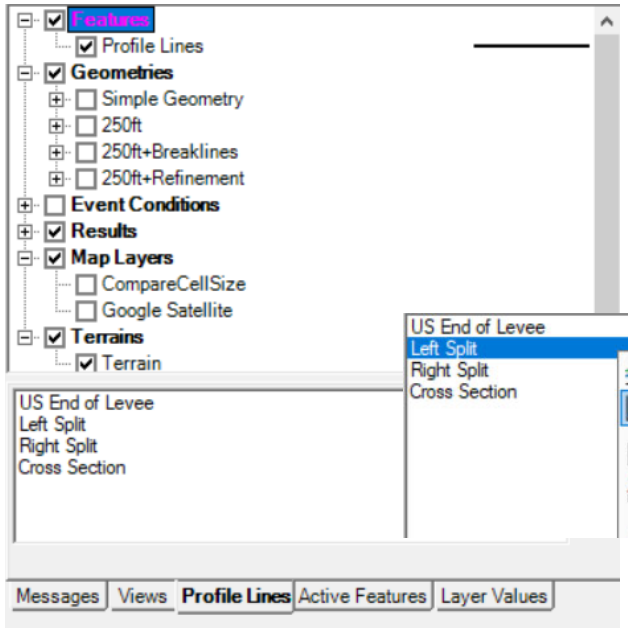
Status Area

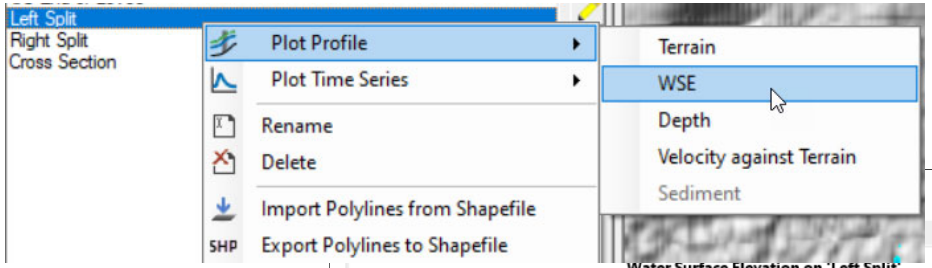
- Messages – What just happened
- View – Quickly zoom to predefined areas
- Profile Lines – Access results at specific locations
- Active Features – Quick access to features in layer
- Layer Values – Watch values for multiple results

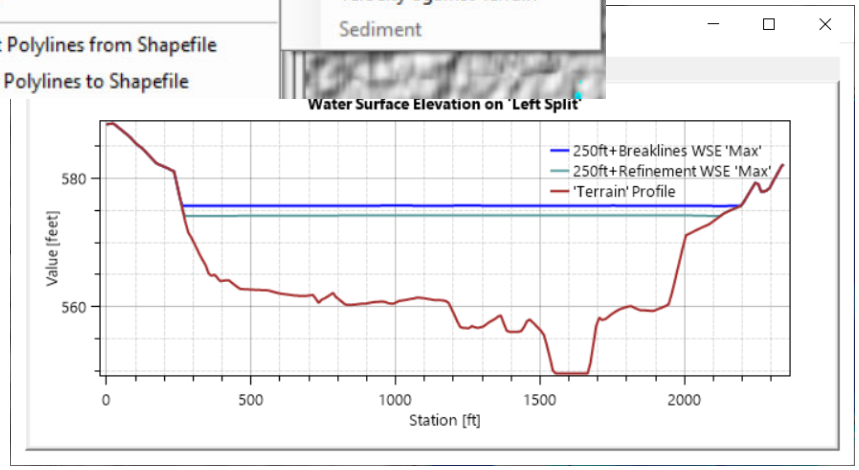


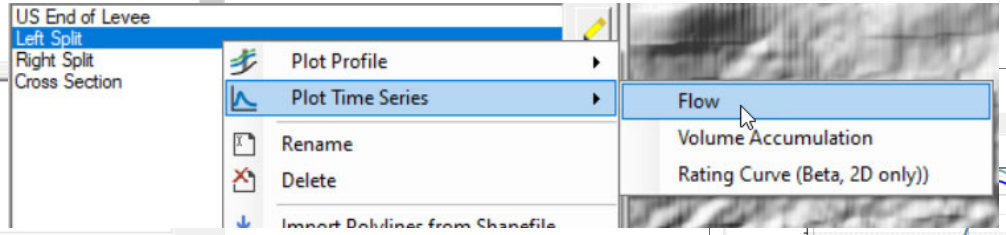
Profile Lines

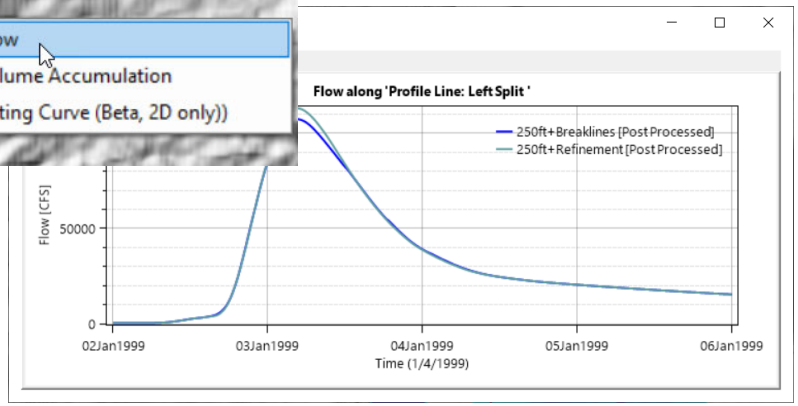
- User-defined/editable features



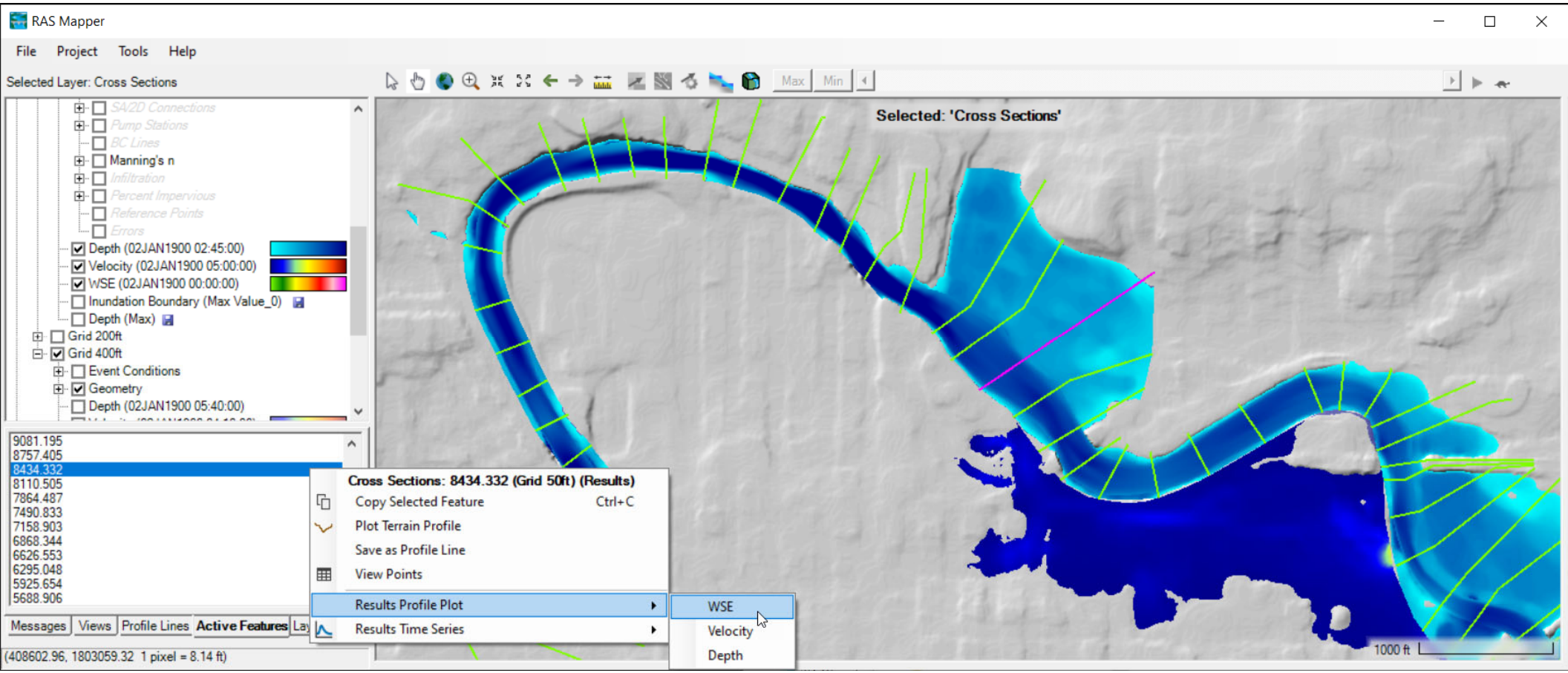




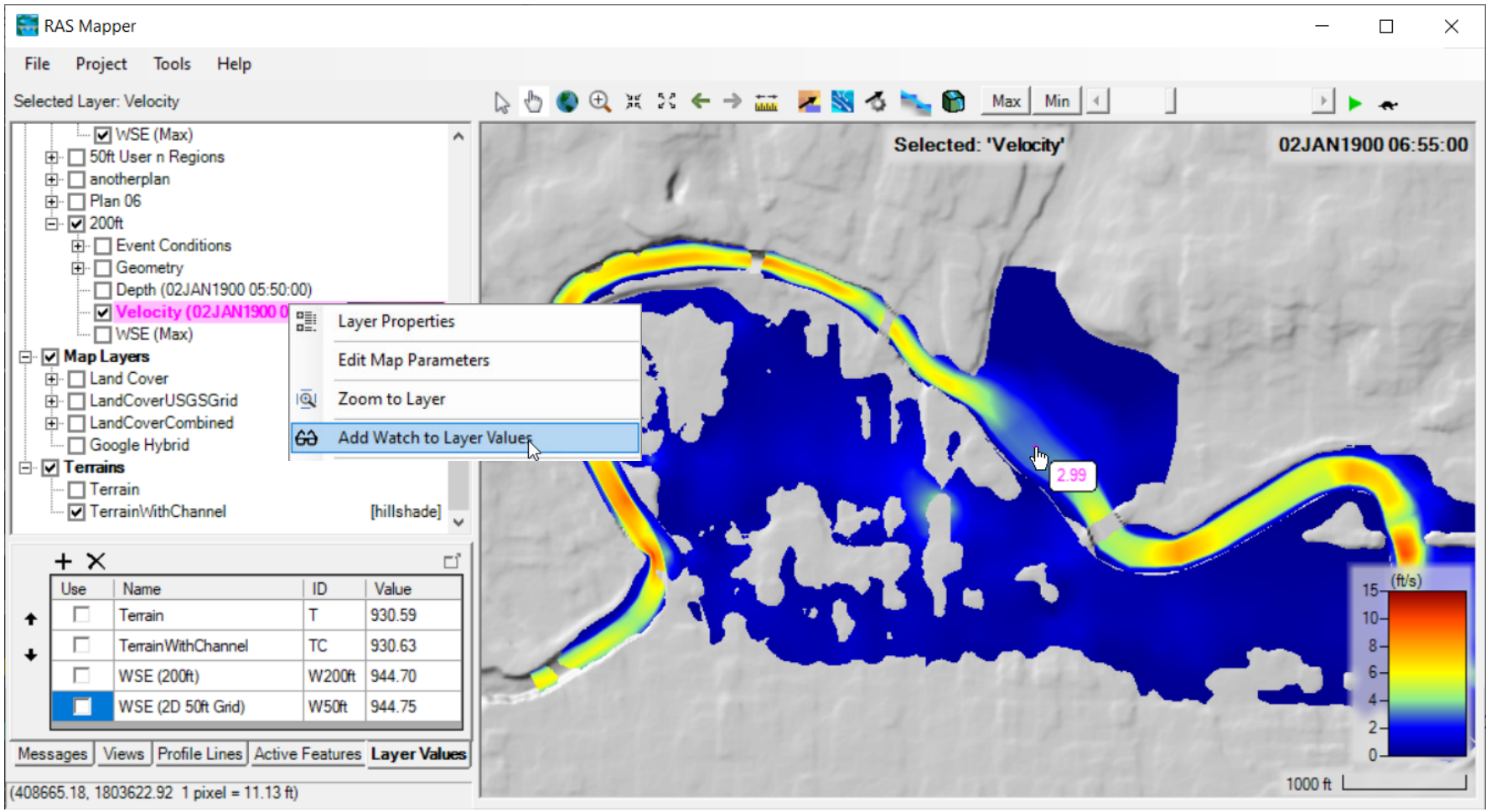




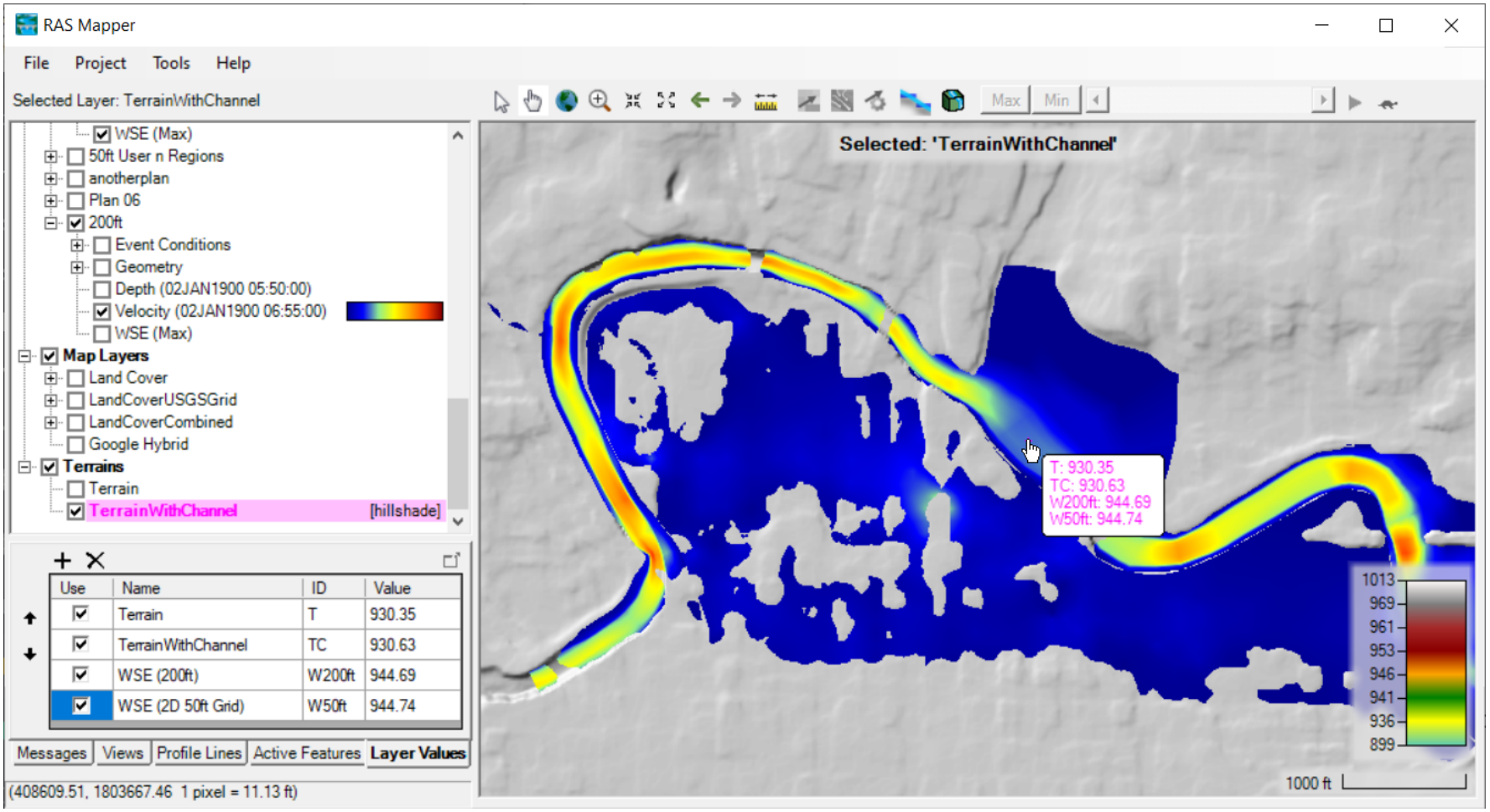
Active Features



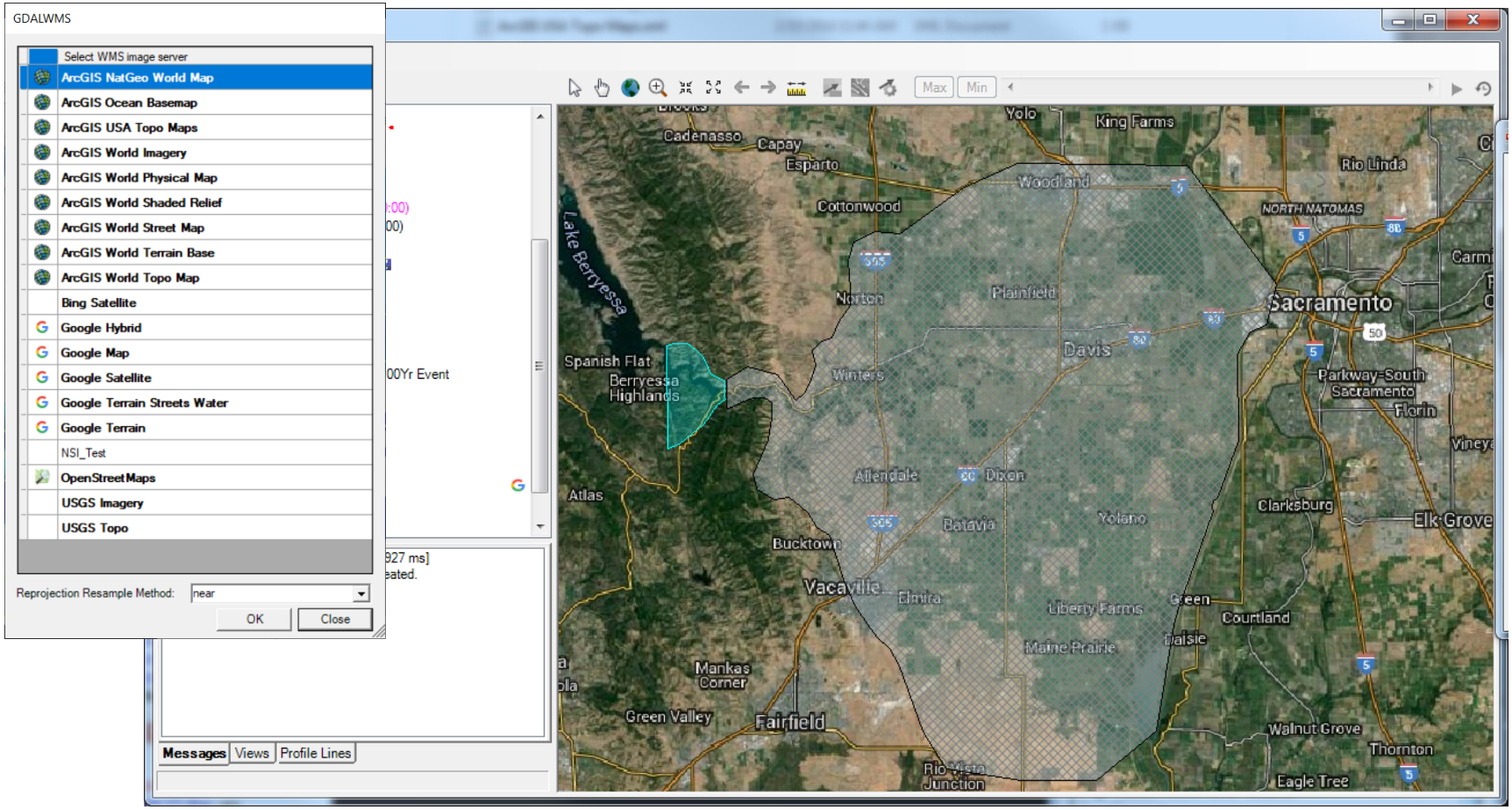
Watch Layers List



Watch Layers List

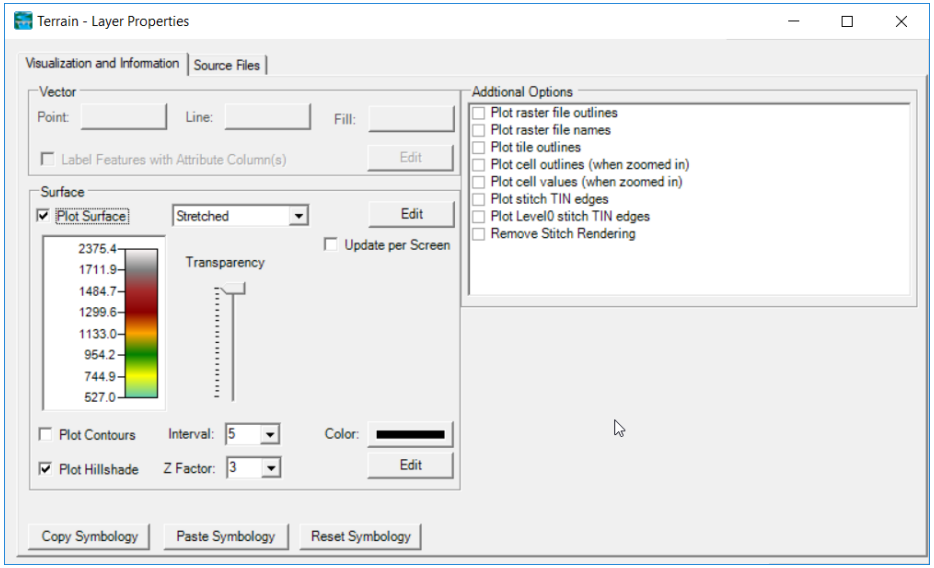


Web Imagery

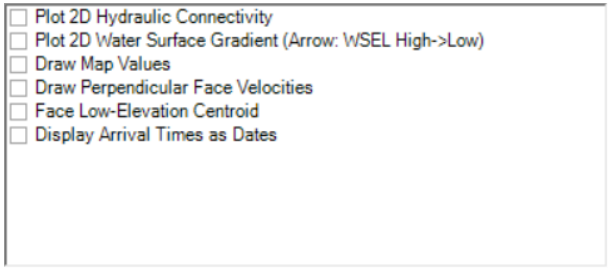

GDALWMS
Select WMS image server
ArcGIS NatGeo World Map
ArcGIS Ocean Basemap
ArcGIS USA Topo Maps
ArcGIS World Imagery
ArcGIS World Physical Map
ArcGIS World Shaded Relief
ArcGIS World Street Map
ArcGIS World Terrain Base
ArcGIS World Topo Map
Bing Satellite
Google Hybrid
Google Map
Google Satellite
Google Terrain Streets Water
Google Terrain
NSI_Test
OpenStreetMaps
USGS Imagery
USGS Topo
Reprojection Resample Method:
near
OK
Close
00Yr Event
Messages
Views
Profile Lines
Max
Min
Cadenasso
Capay
Esparto
Yolo
King Farms
Rio Linda
Woodland
Cottonwood
NORTH NATOMAS
Lake Berryessa
Norton
Plainfield
Sacramento
Davis
Spanish Flat
Berryessa Highlands
Winters
Parkway-South Sacramento
Florin
Allendale
Dixon
Atlas
Clarksburg
Elk Grove
Batavia
Yolano
Bucktown
Vacaville
Elmira
Liberty Farms
Courtland
Maine Prairie
Mankas Corner
Green Valley
Fairfield
Walnut Grove
Thornton
Rio Vista Junction
Eagle Tree

Plot Options – Layer Specific!

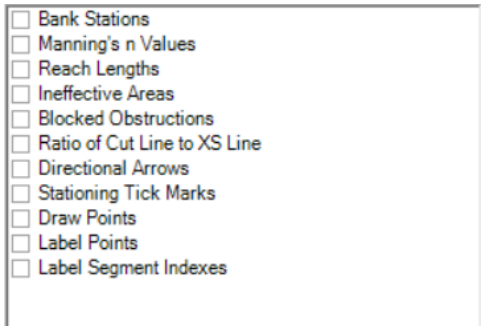
- Terrain



- Depth, WSE

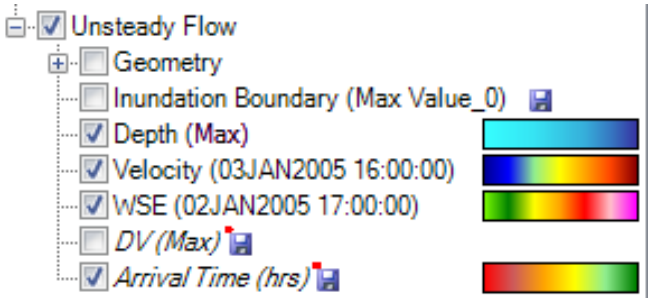


- River, Cross Sections



Results Mapping

- Dynamic Mapping – on-the-fly mapping
  - Animation of results without waiting

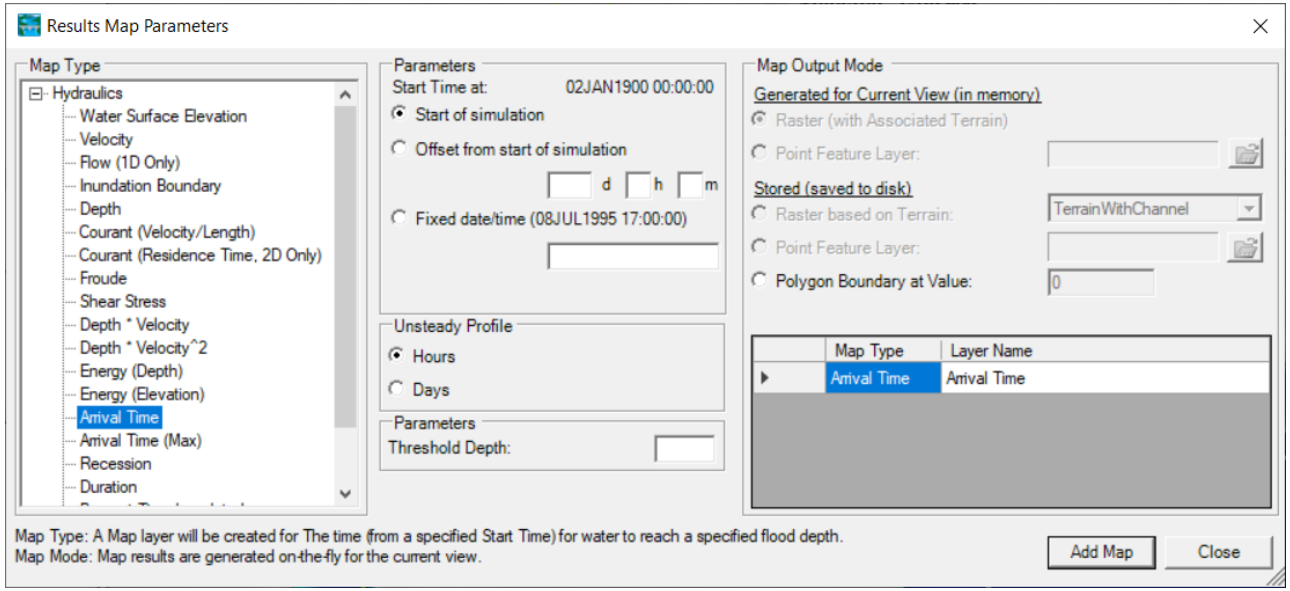


- Stored Maps – results written to file

* *= There was a problem reading data*

Results Mapping

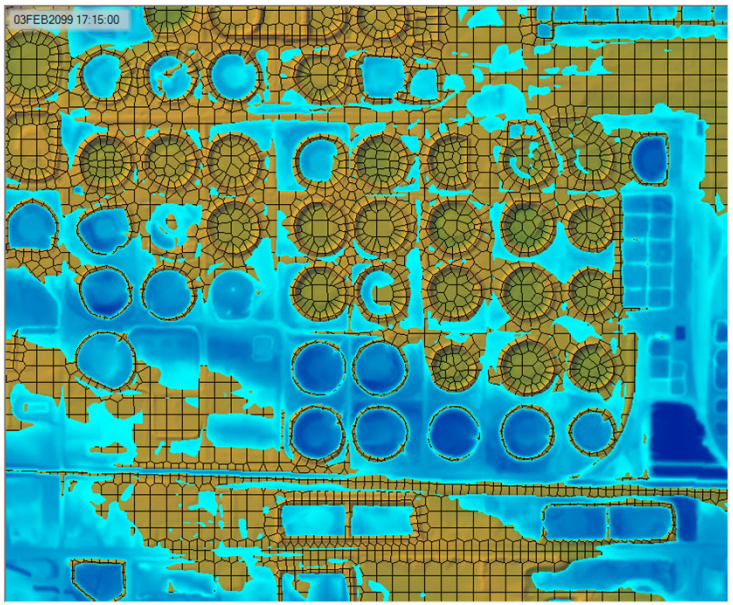
Map Type | Profile/Parameter | Mode



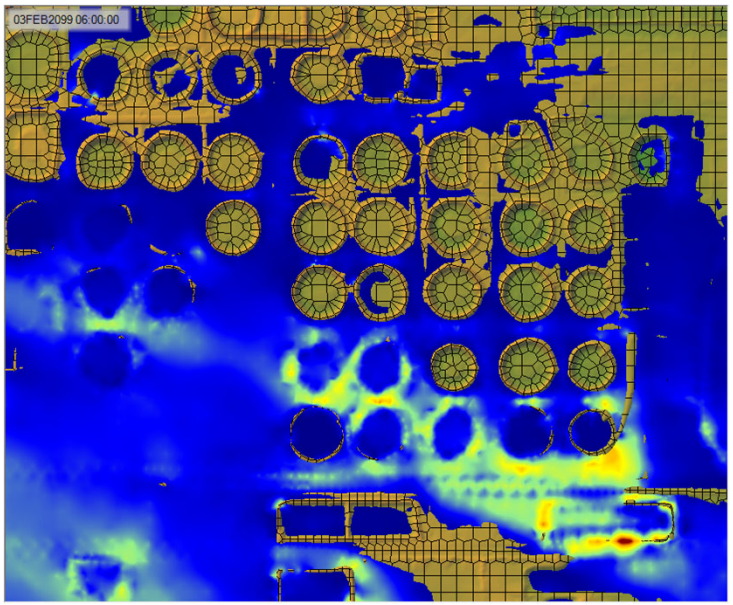
Default maps: Depth, Water Surface Elevation, Velocity

Example Maps

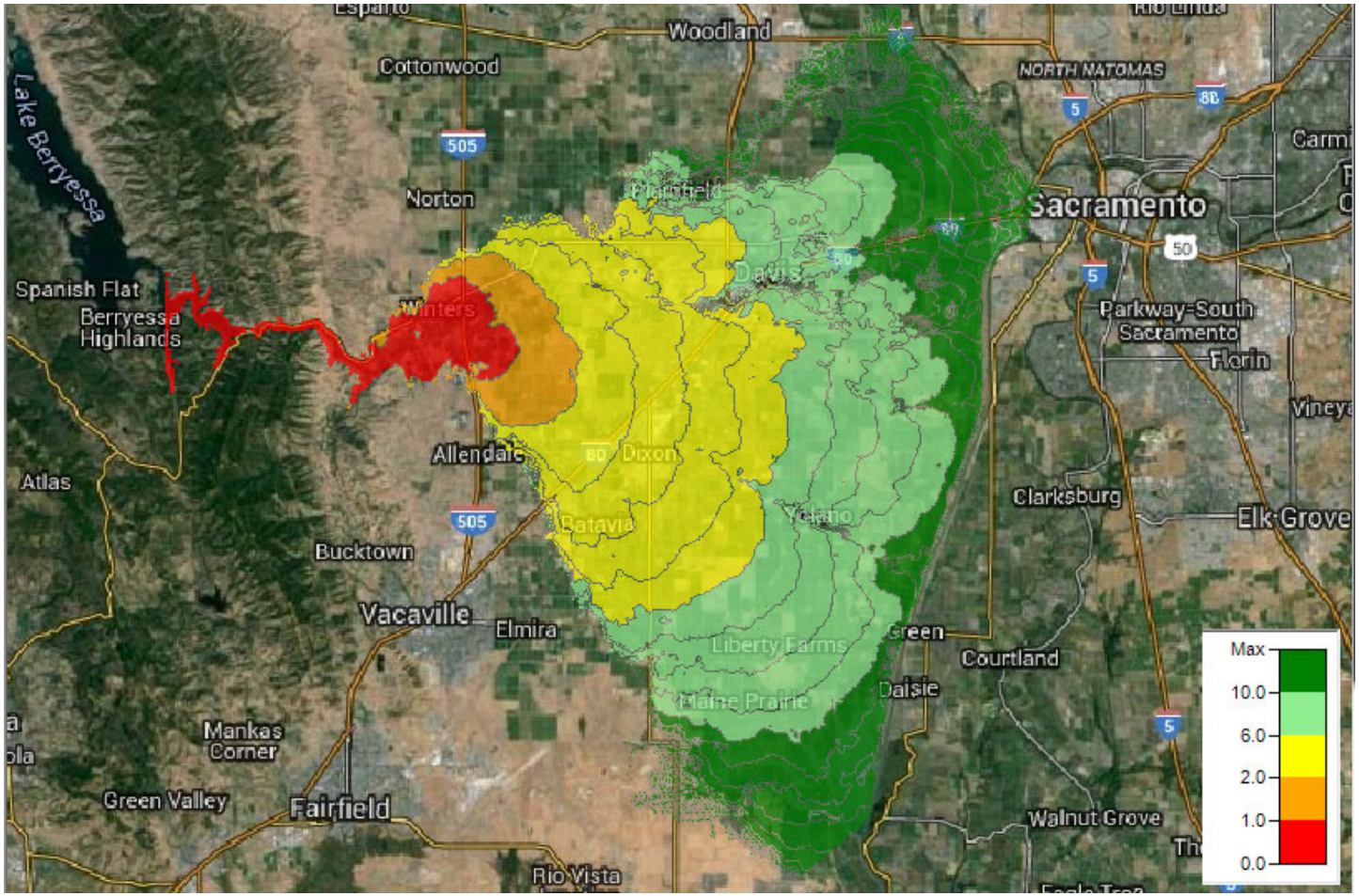
- Depth



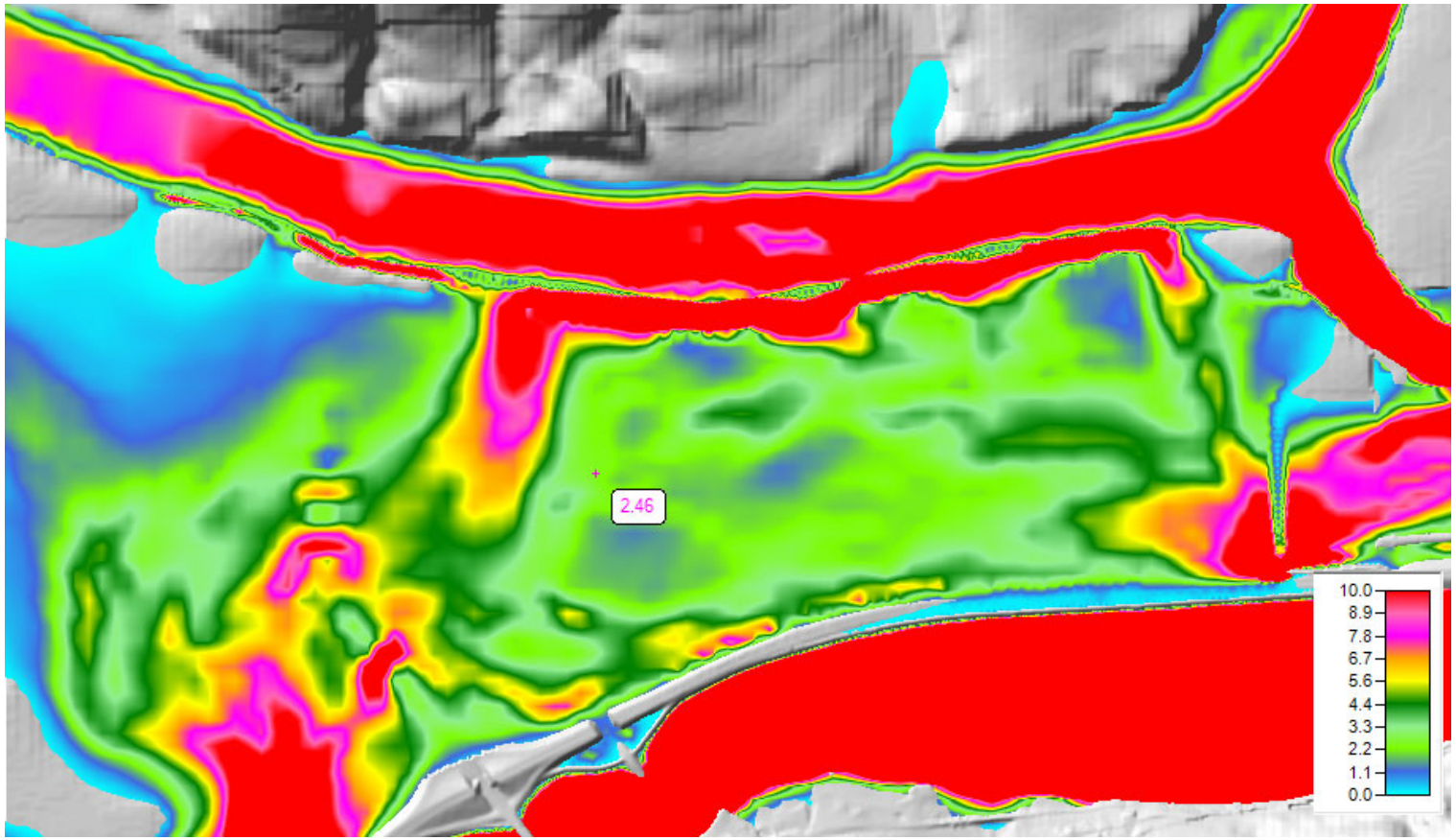
- Velocity



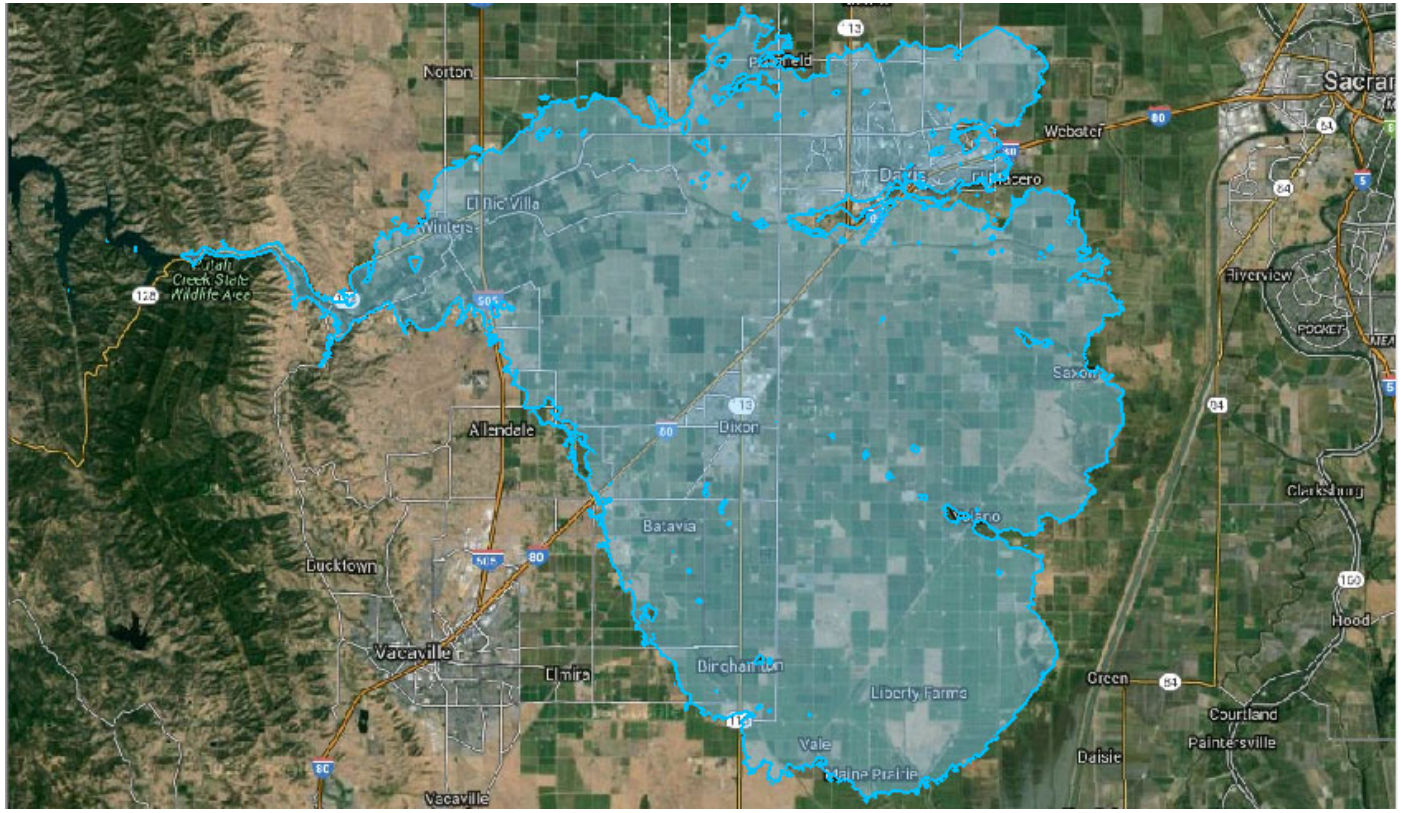
Arrival Time



Hazard Mapping



Inundation Boundary

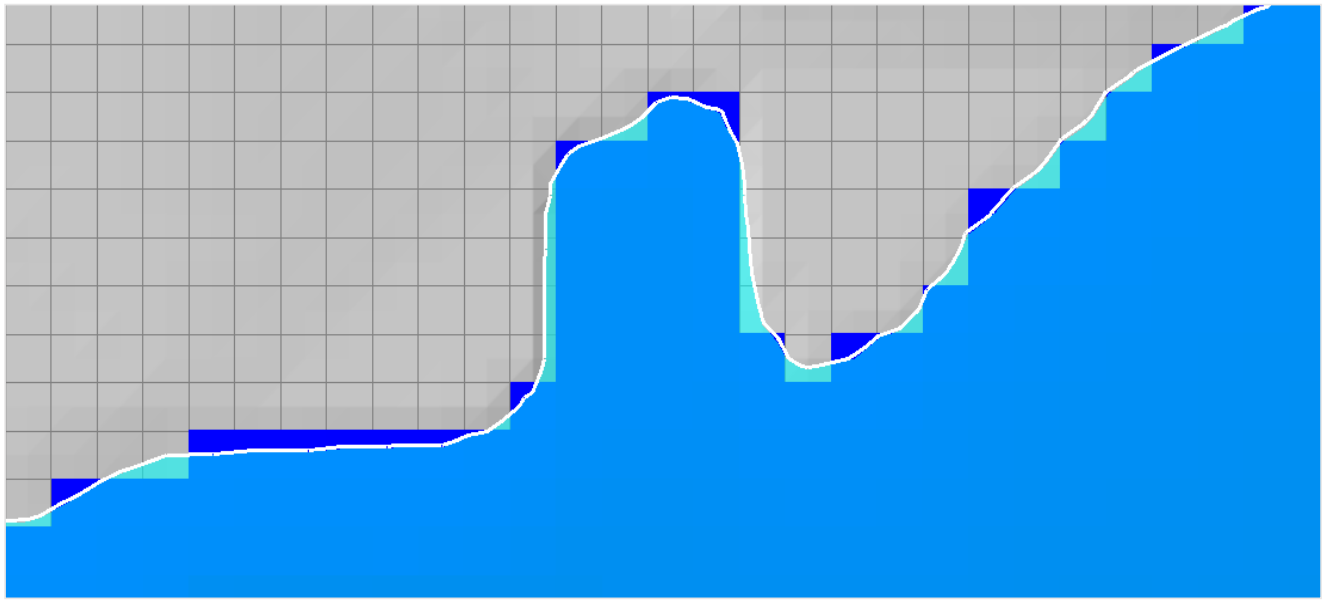


Map Types – Dynamic vs Stored

- Dynamic: Computed on-the-fly
  - Smooth: Computes to screen-resolution
  - Doesn’t use disk space
- Stored: Computed to terrain resolution
  - Stored to disk
  - Faster rendering for slow map types

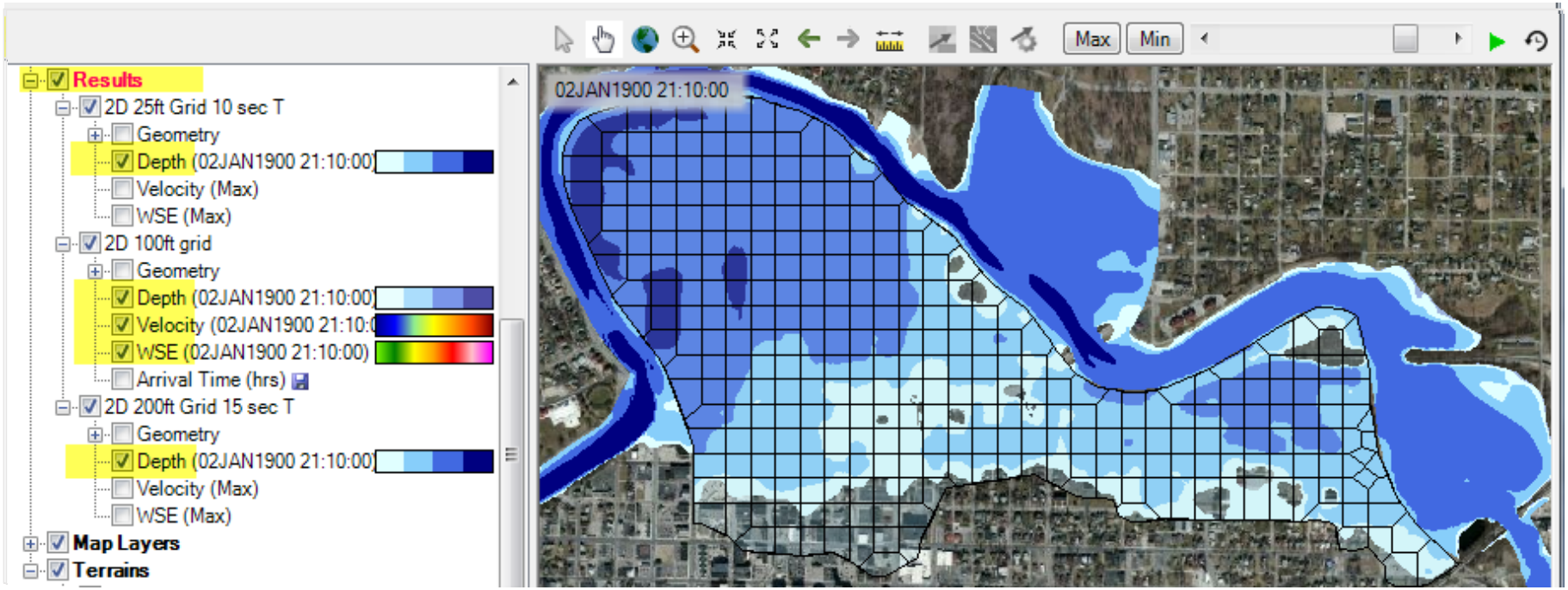
Dynamic vs Stored Results

- Dynamic results plot values for the current pyramid level. Boundaries are defined based on interpolation.
- Stored results have a single value per cell.

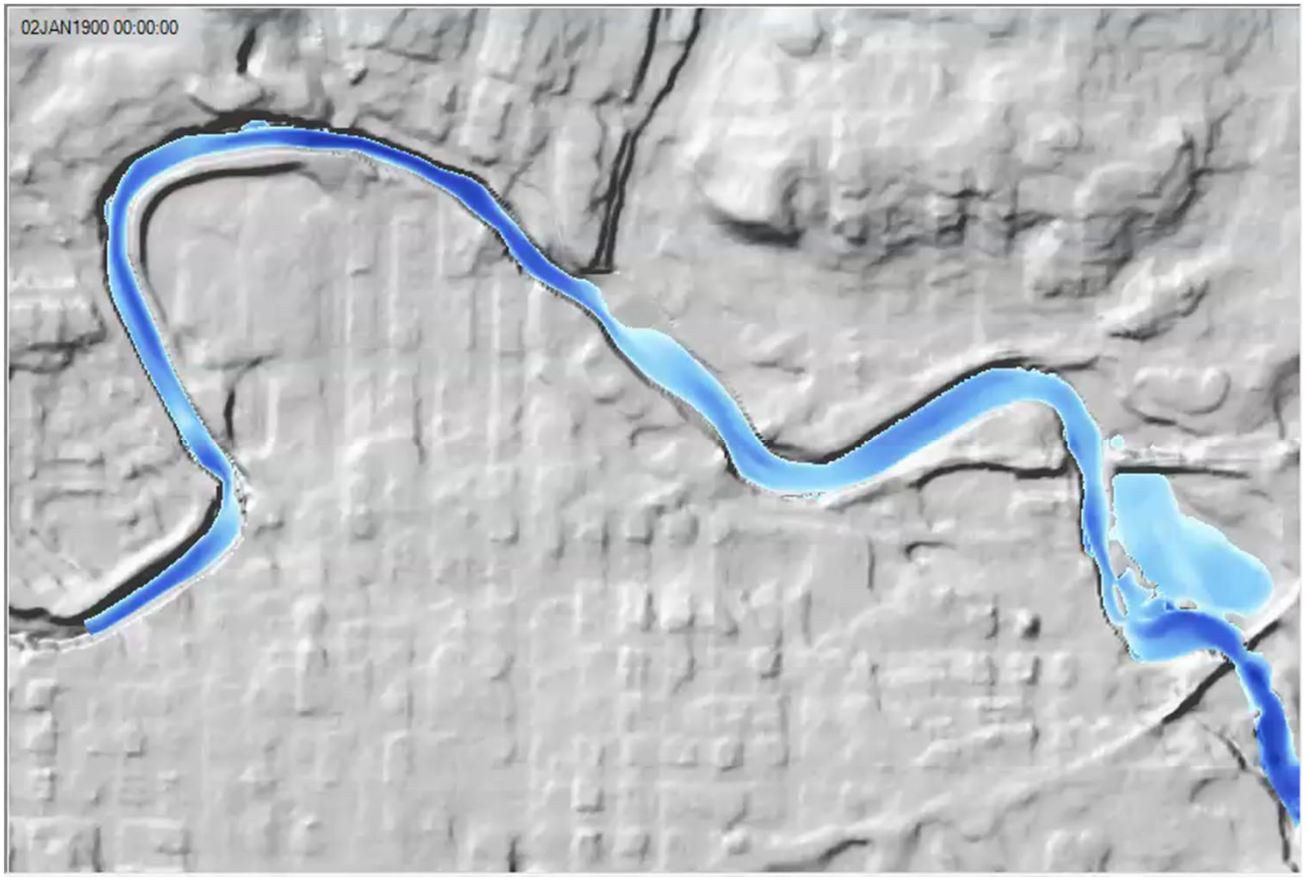


Dynamic Mapping

- Animation Toolbar – works on selected layer/group and syncs the timestep

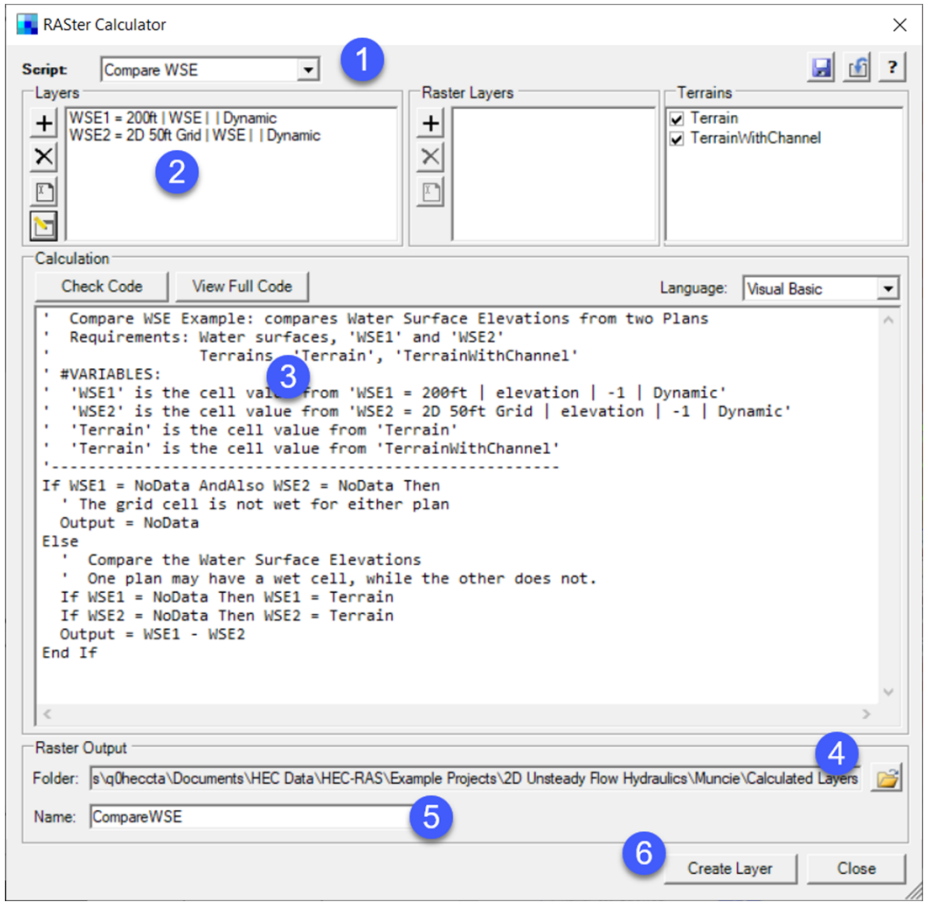


Dynamic Mapping - Animation



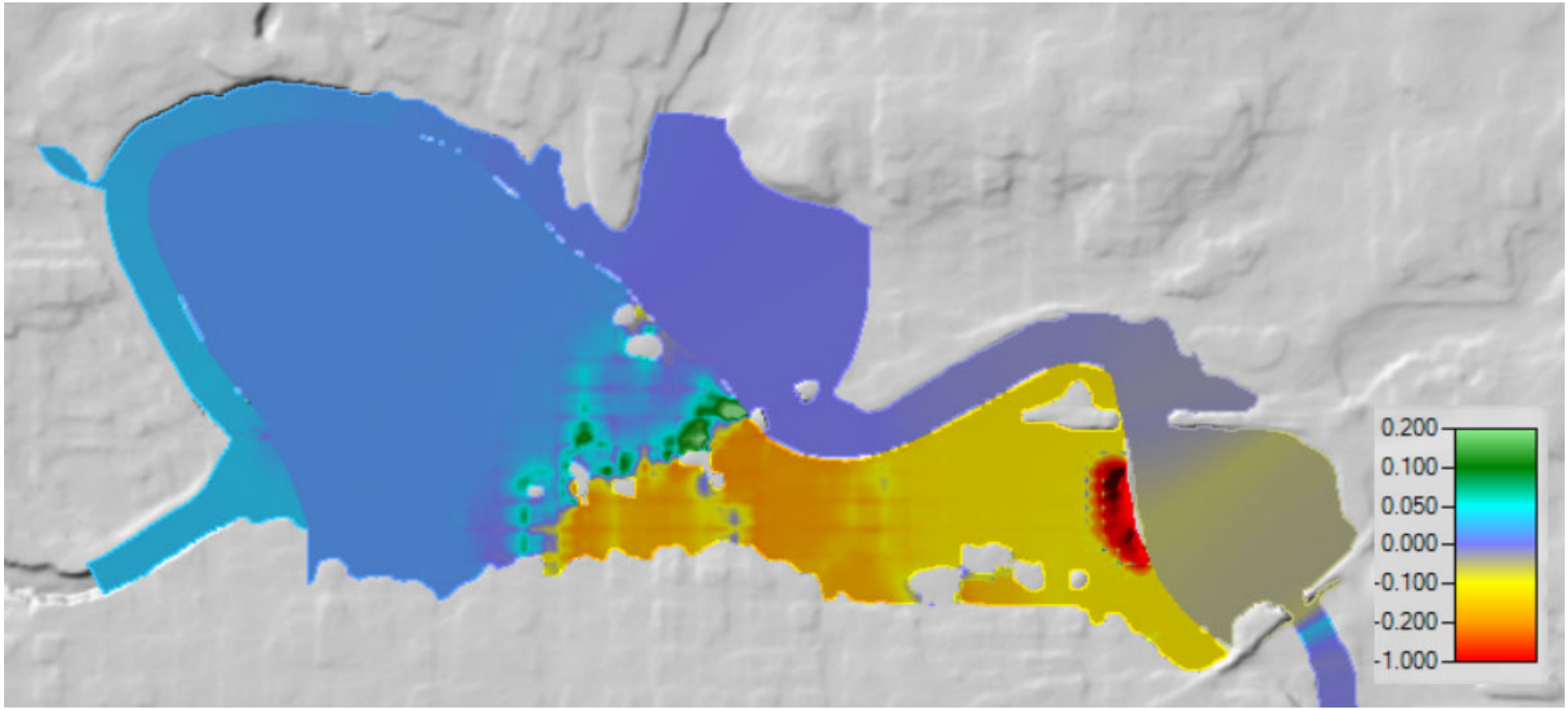
Calculated Layer

- RASter Calculator
- Custom scripting code to use multiple results
- Works with RAS Results and Terrains
- Works with Rasters on disk

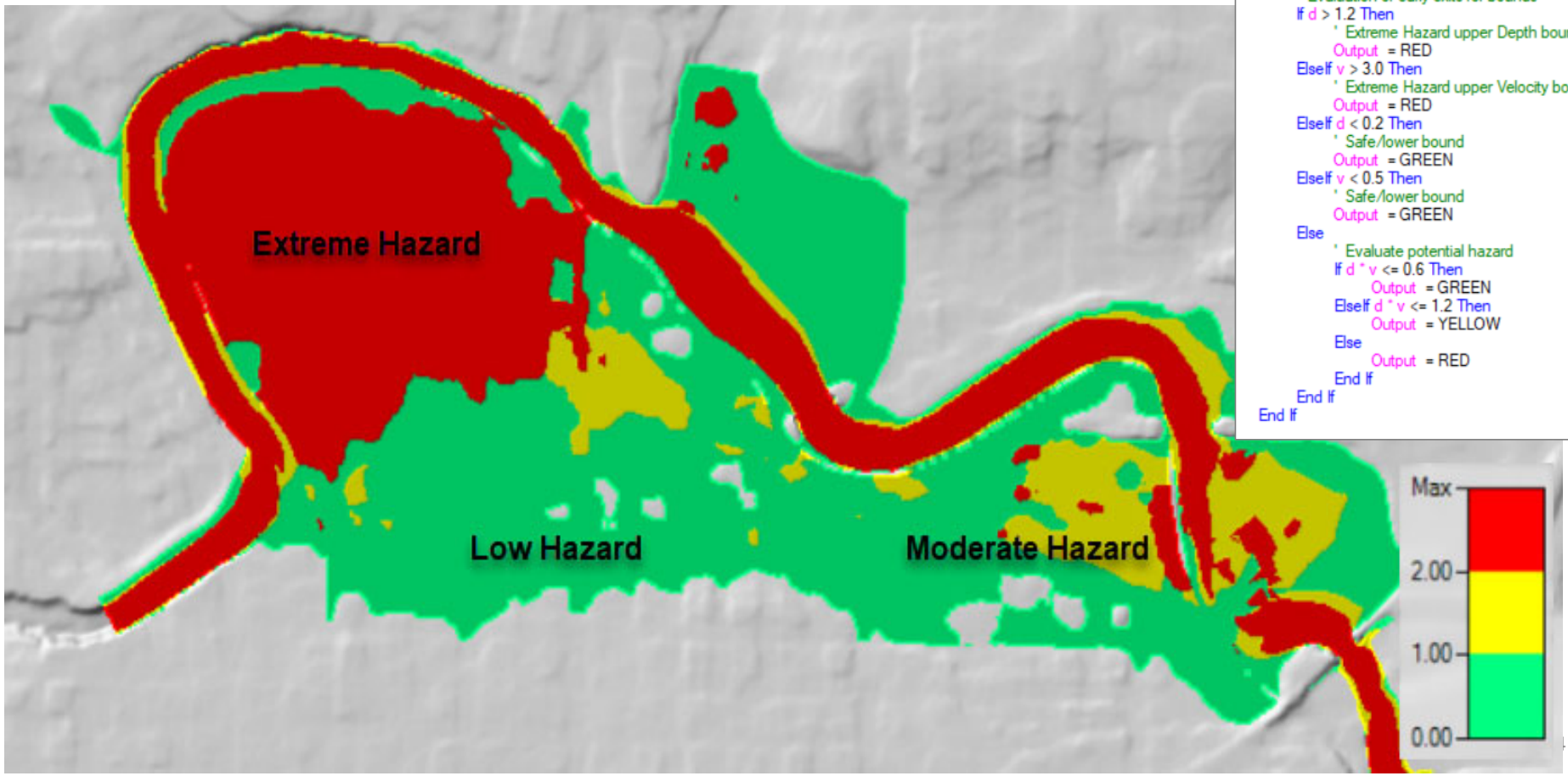


Water Surface Comparison

WSE_Mesh200ft - WSE_Mesh50ft



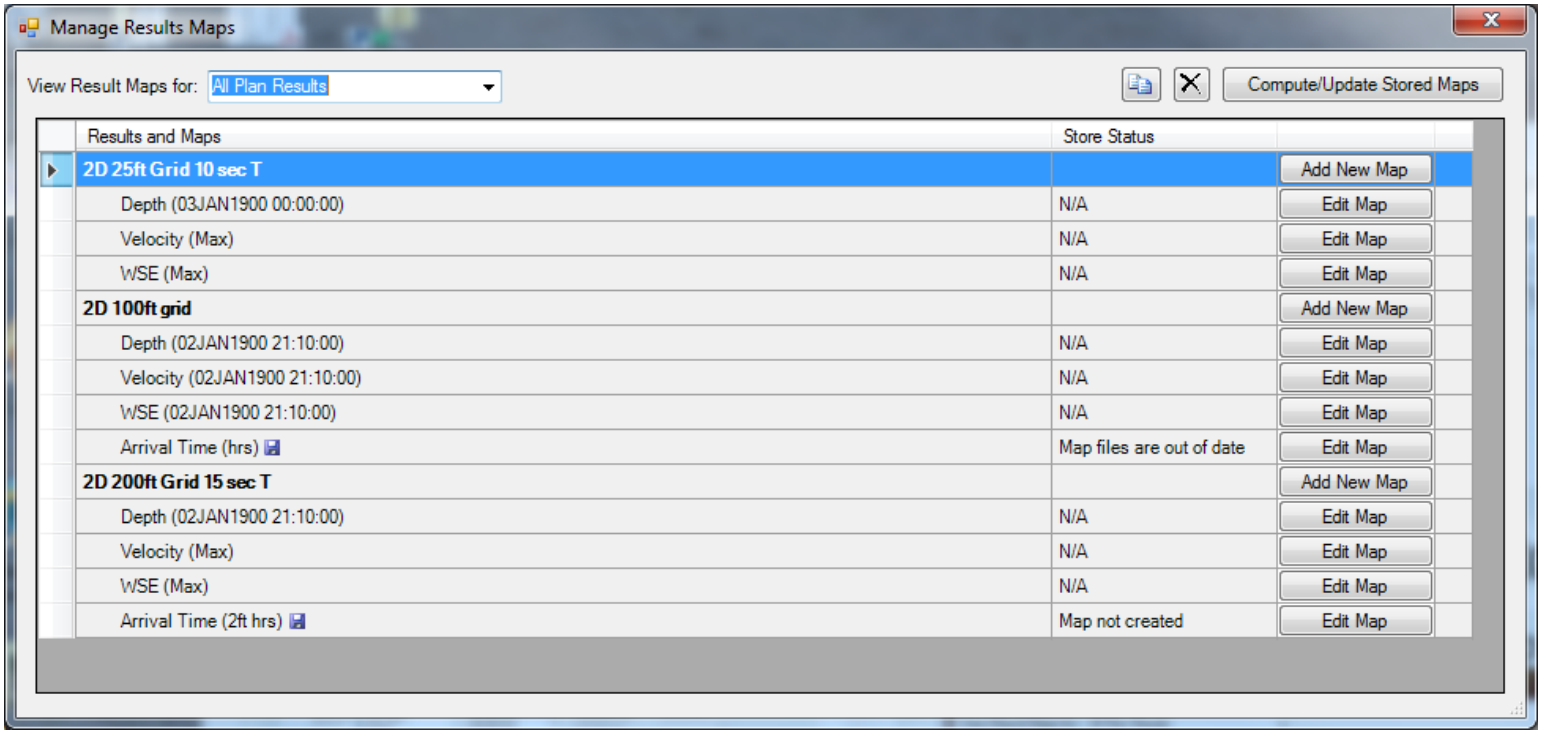
Hazard Evaluation



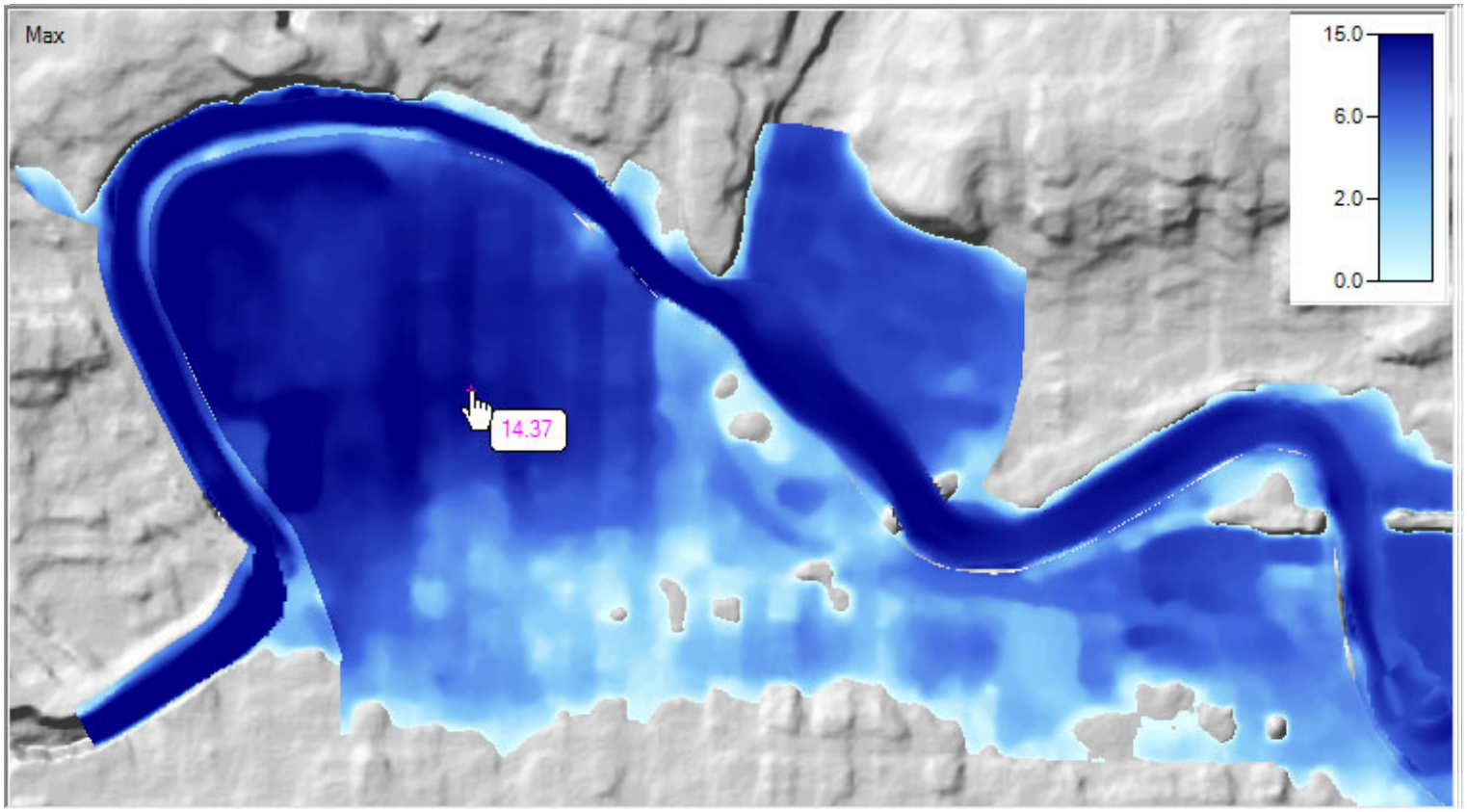

```
Const GREEN as Single = 0
Const YELLOW as Single = 1
Const RED as Single = 2

If d = NoData OrElse v = NoData Then
    Output = NoData
Else
    ' Conversion to metric assuming input variables are in feet
    d = d * 0.3048
    v = v * 0.3048
    ' Evaluation of early exits for bounds
    If d > 1.2 Then
        ' Extreme Hazard upper Depth bound
        Output  = RED
    ElseIf v > 3.0 Then
        ' Extreme Hazard upper Velocity bound
        Output  = RED
    ElseIf d < 0.2 Then
        ' Safe/lower bound
        Output  = GREEN
    ElseIf v < 0.5 Then
        ' Safe/lower bound
        Output  = GREEN
    Else
        ' Evaluate potential hazard
        If d * v <= 0.6 Then
            Output  = GREEN
        ElseIf d * v <= 1.2 Then
            Output  = YELLOW
        Else
            Output  = RED
        End If
    End If
End If
```

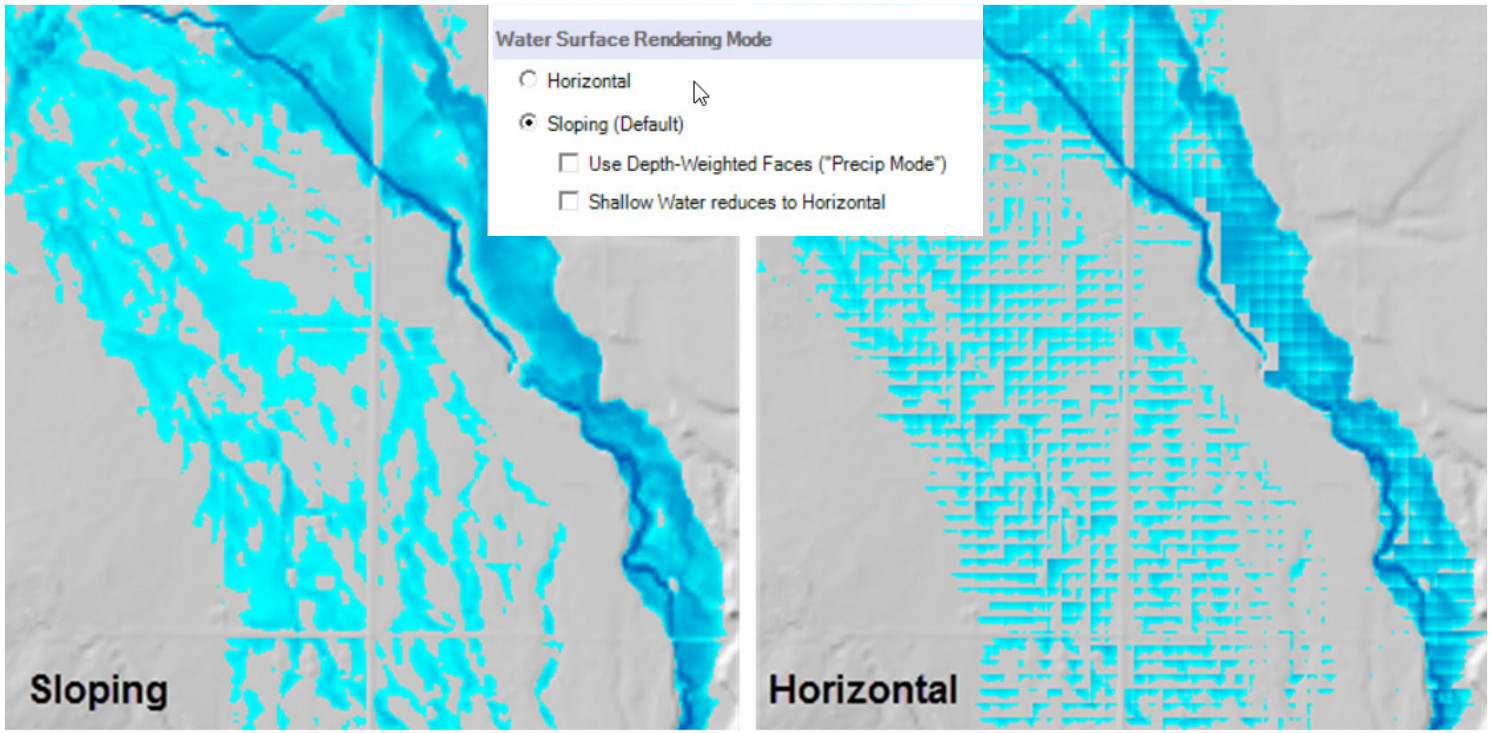
Stored Maps


Manage Results Maps
View Result Maps for:
All Plan Results
Compute/Update Stored Maps
Results and Maps
Store Status
2D 25ft Grid 10 sec T
Add New Map
Depth (03JAN1900 00:00:00)
N/A
Edit Map
Velocity (Max)
N/A
Edit Map
WSE (Max)
N/A
Edit Map
2D 100ft grid
Add New Map
Depth (02JAN1900 21:10:00)
N/A
Edit Map
Velocity (02JAN1900 21:10:00)
N/A
Edit Map
WSE (02JAN1900 21:10:00)
N/A
Edit Map
Arrival Time (hrs)
Map files are out of date
Edit Map
2D 200ft Grid 15 sec T
Add New Map
Depth (02JAN1900 21:10:00)
N/A
Edit Map
Velocity (Max)
N/A
Edit Map
WSE (Max)
N/A
Edit Map
Arrival Time (2ft hrs)
Map not created
Edit Map

Results Visualization

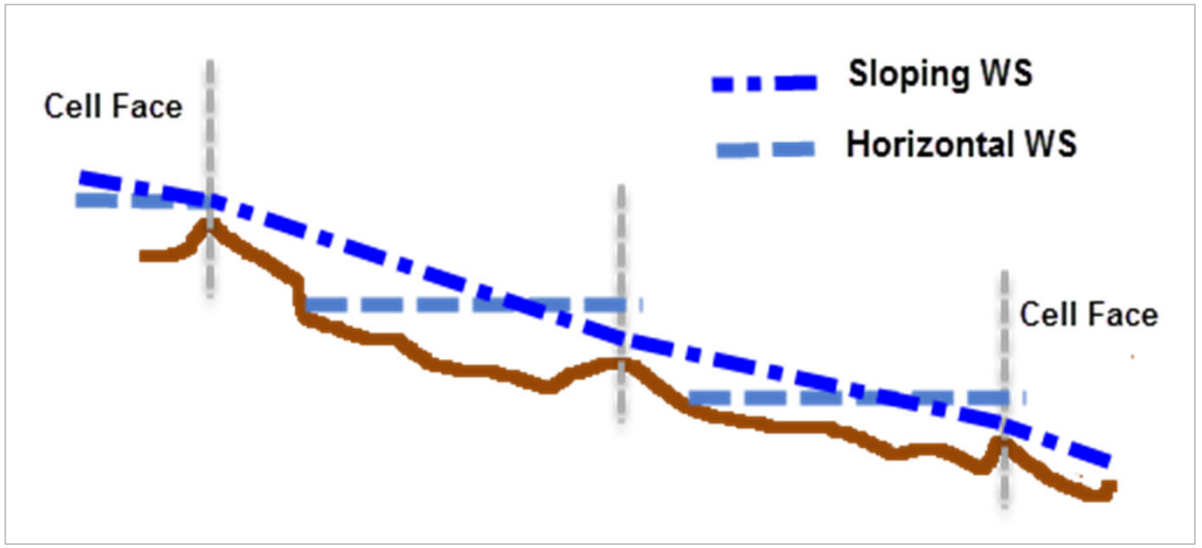


Render Mode Options

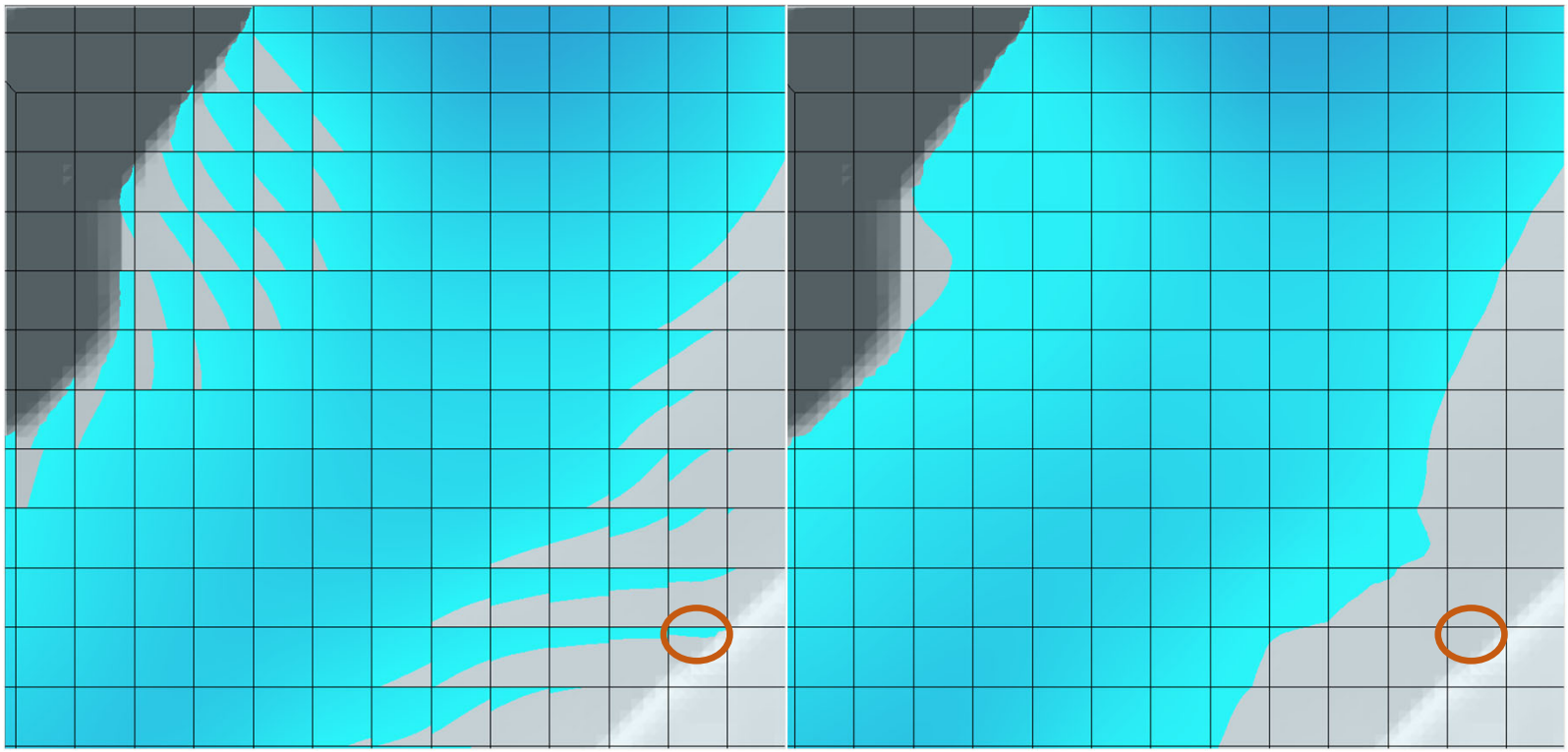


Results Interpolation

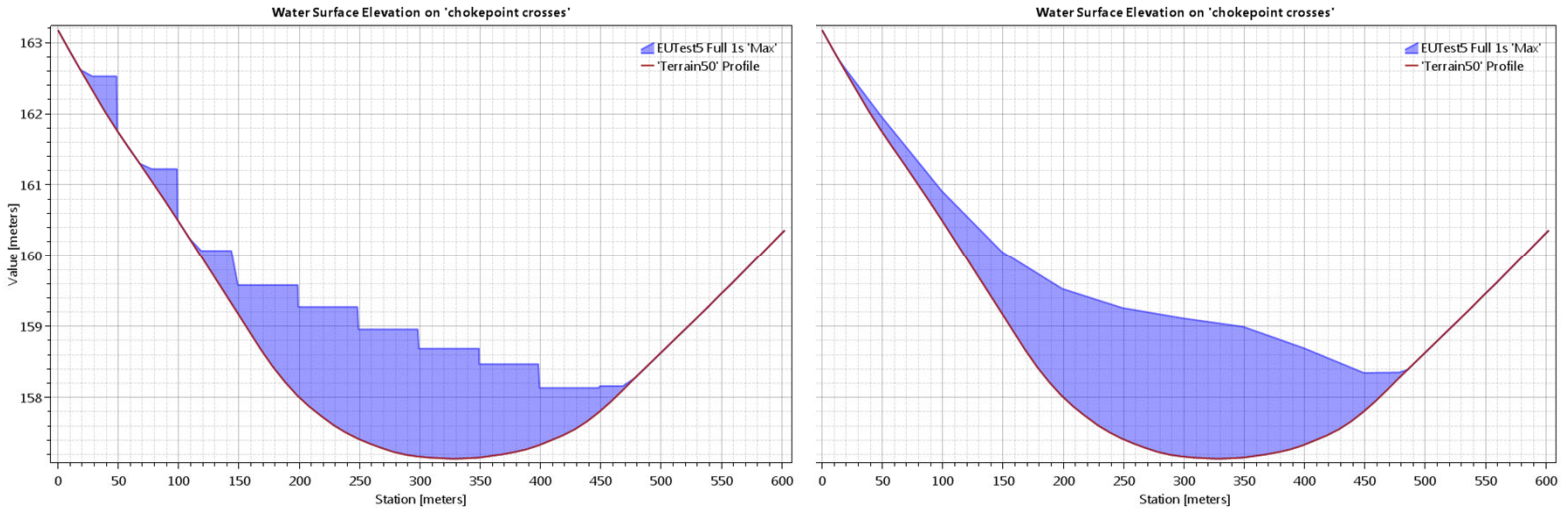
- Render mode options allow for interpolation of water surface elevation values or plotting values at the cell centers.



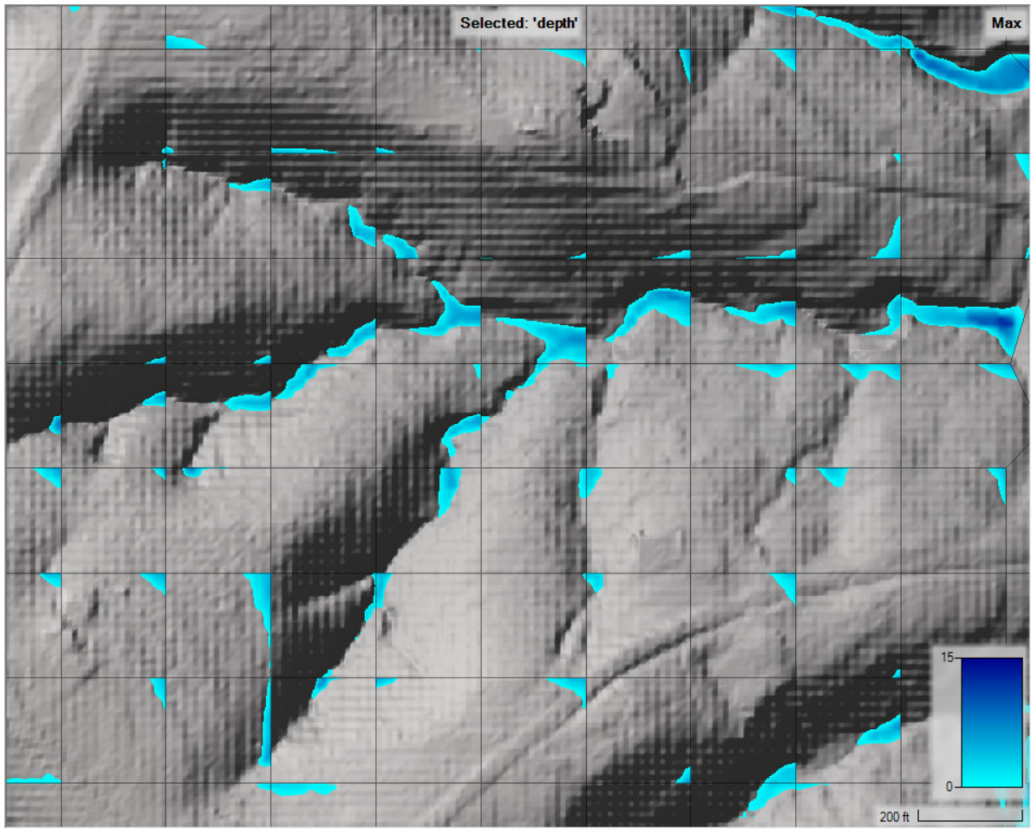
Horizontal vs Sloping Surface



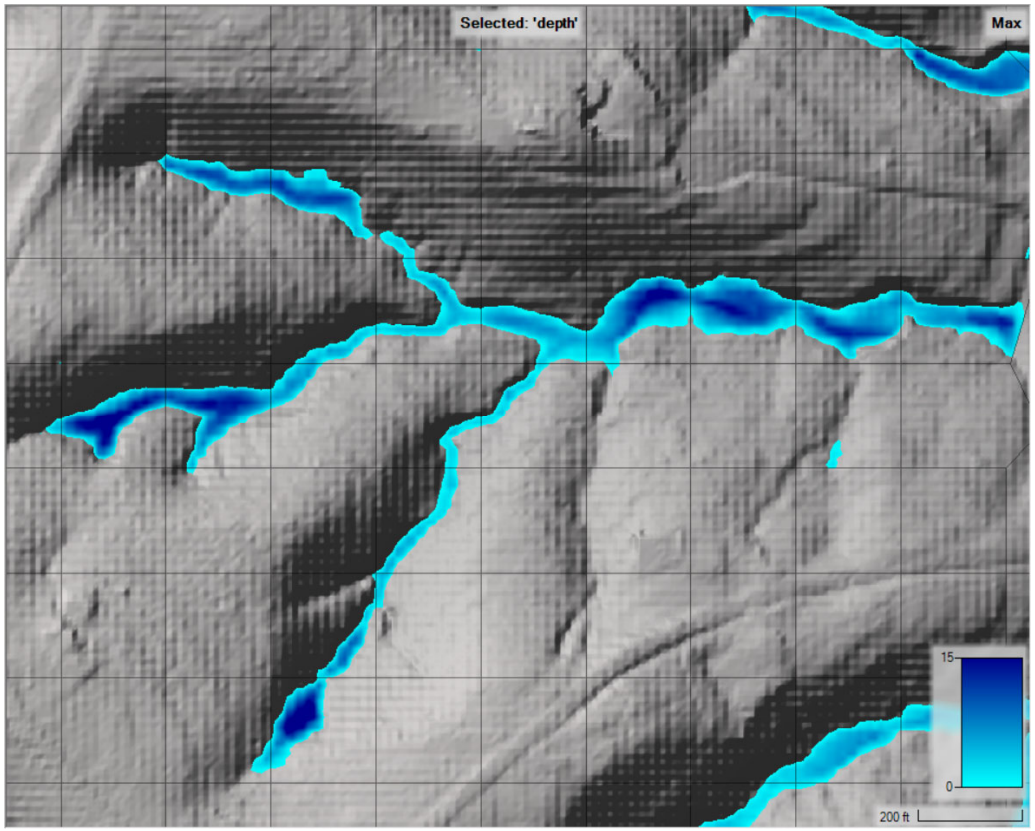
Horizontal vs Sloping Surface



Sloping Surface Errors

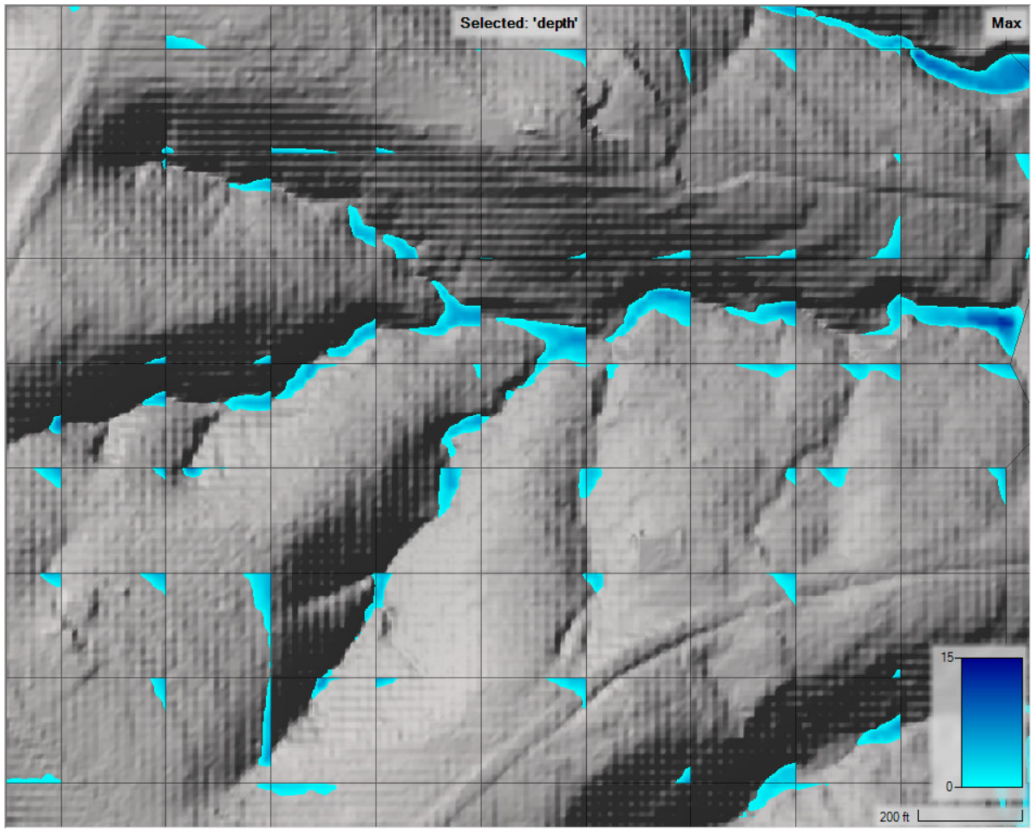


Horizontal

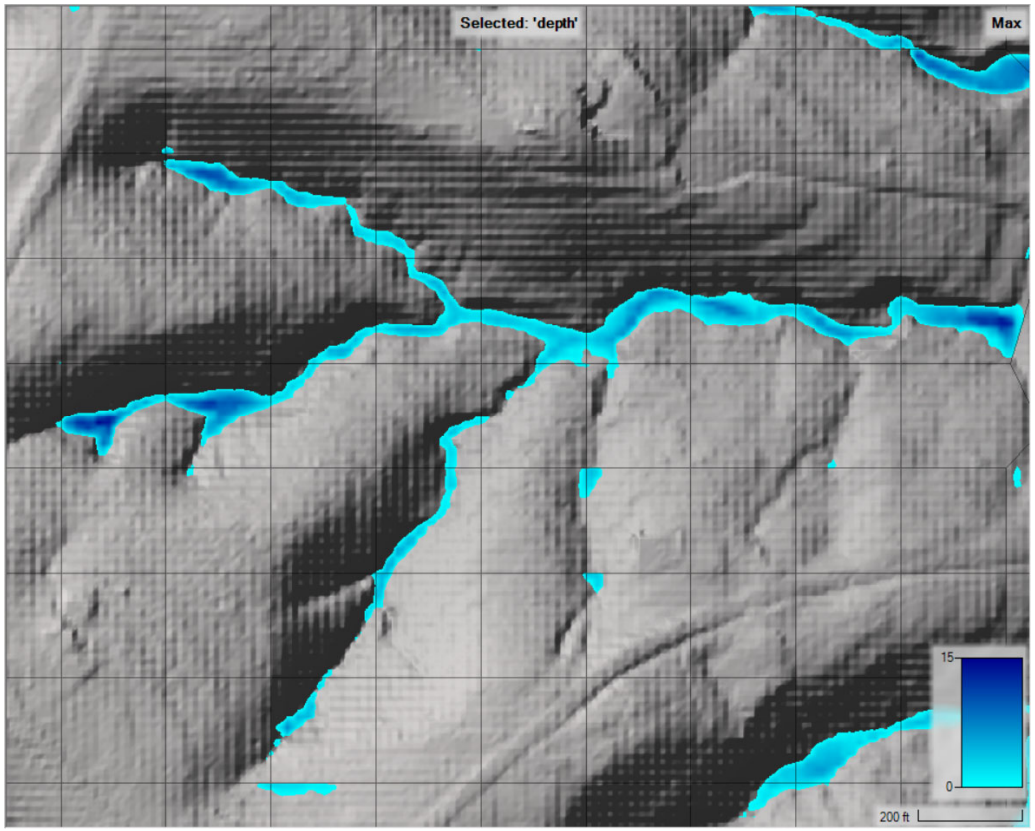


Sloping

Sloping Surface Errors



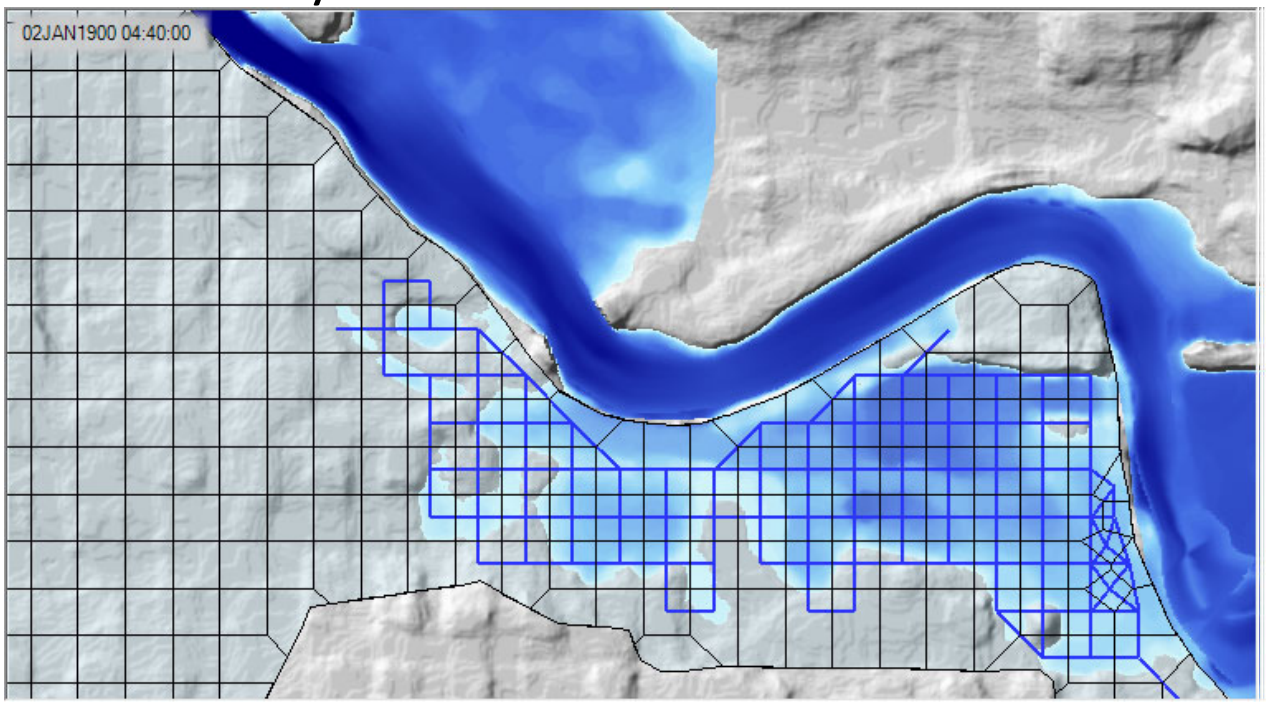
Horizontal



Precip Mode

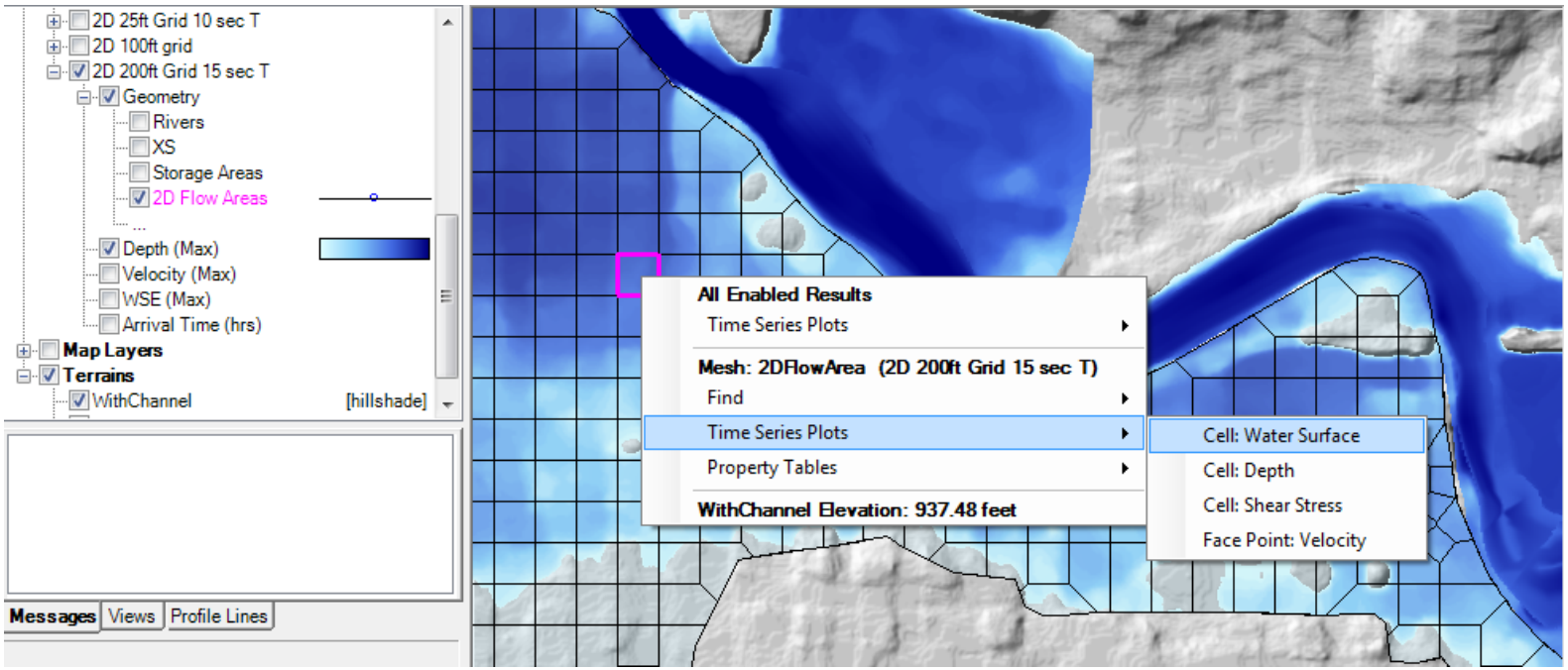
Depth Results

- Hydraulic connectivity from mesh



Results Query

- 2D Flow Area query



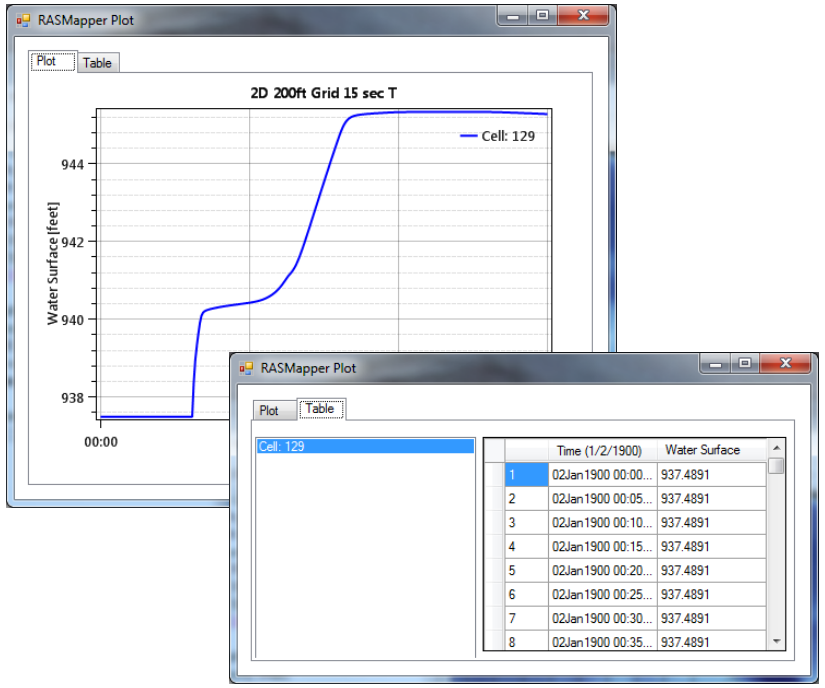
2D Flow Area Queries

- Hydraulic Properties

  - Cell: Volume - Elevation
  - Face: Area - Elevation
  - Face: Wetted Perimeter - Elevation
  - Face: Manning's n - Elevation
  - Face: Profile

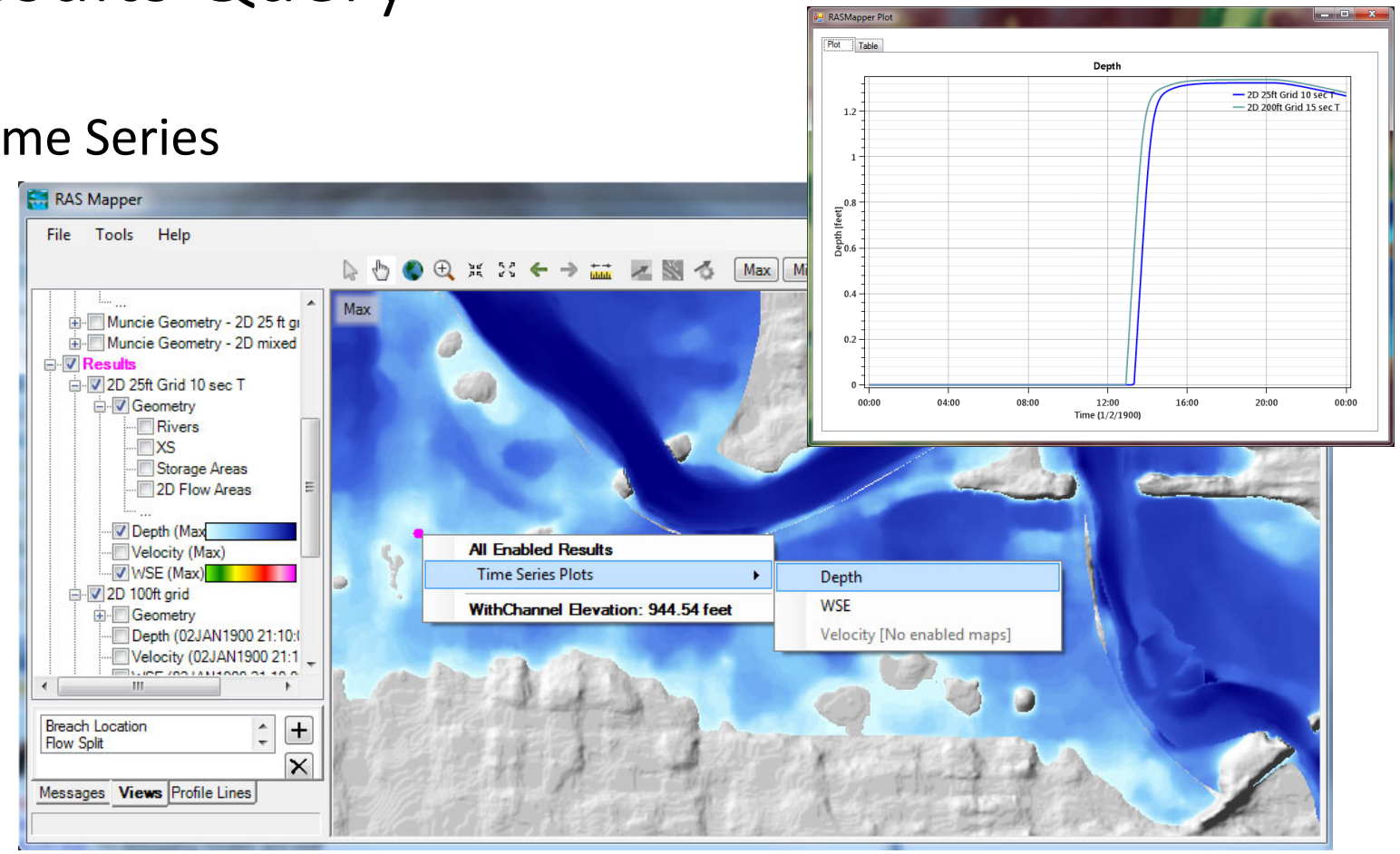
- Time Series

  - Cell: Water Surface
  - Cell: Depth
  - Cell: Shear Stress
  - Face Point: Velocity

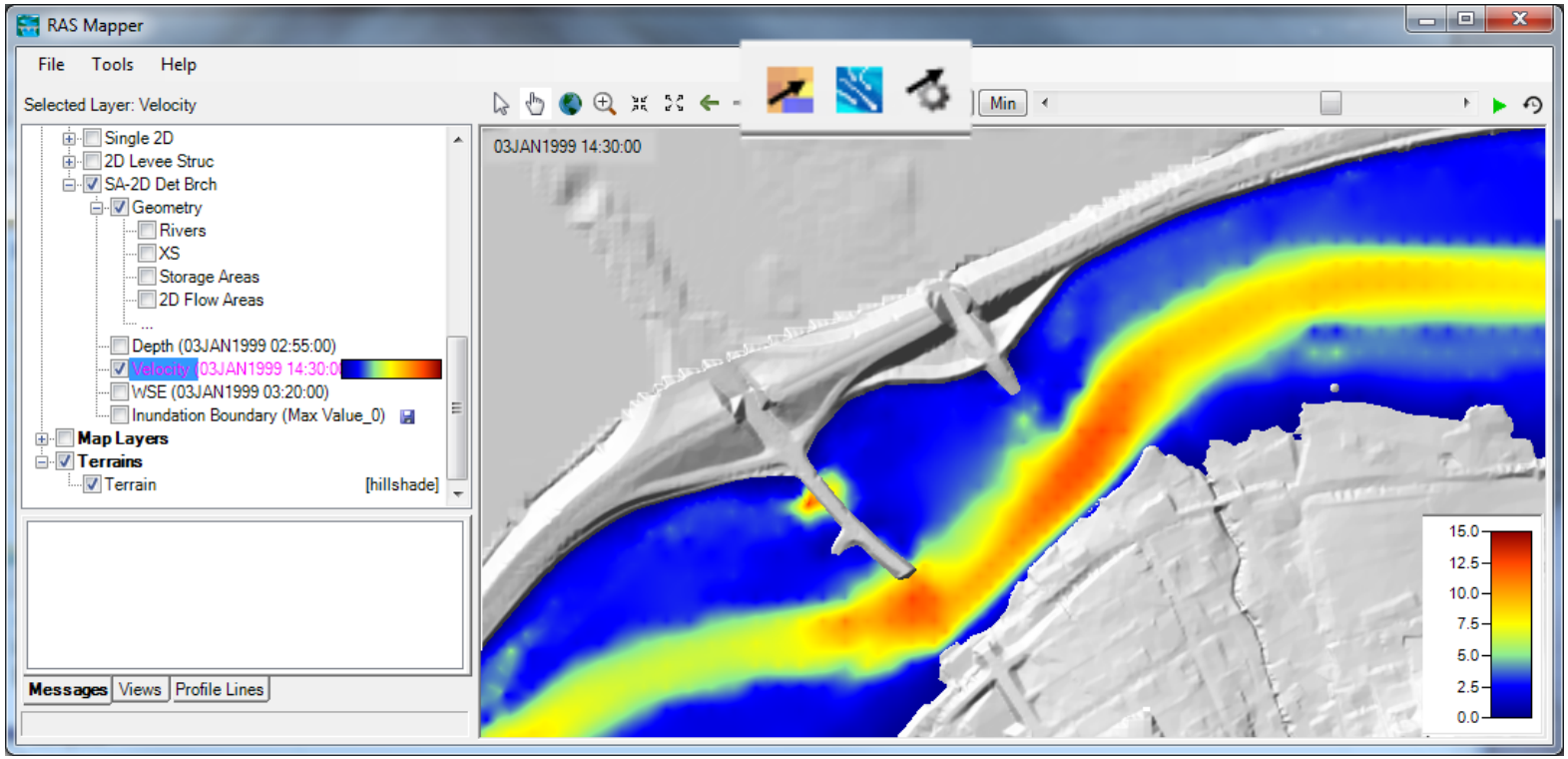


Results Query

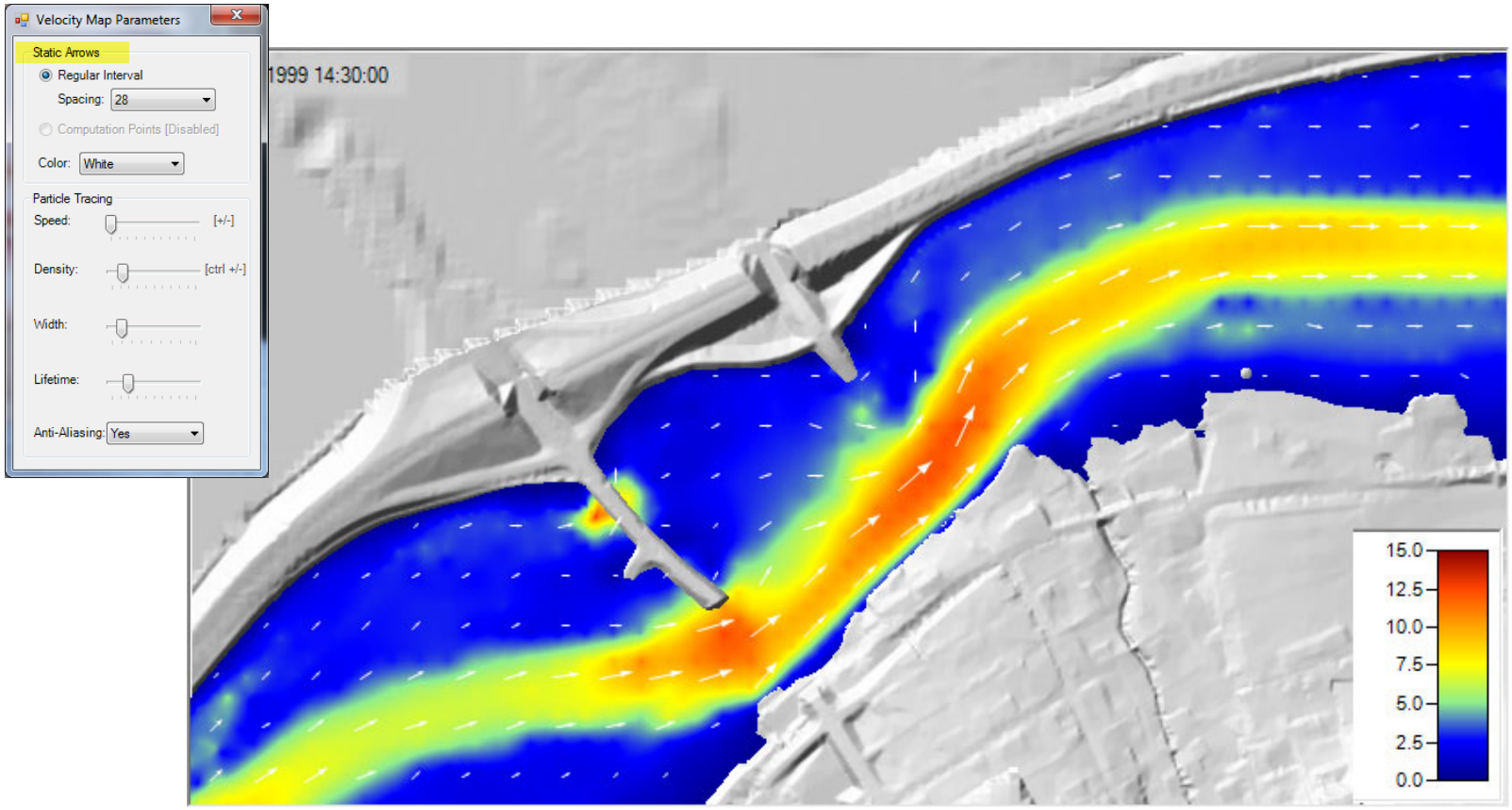
- Time Series



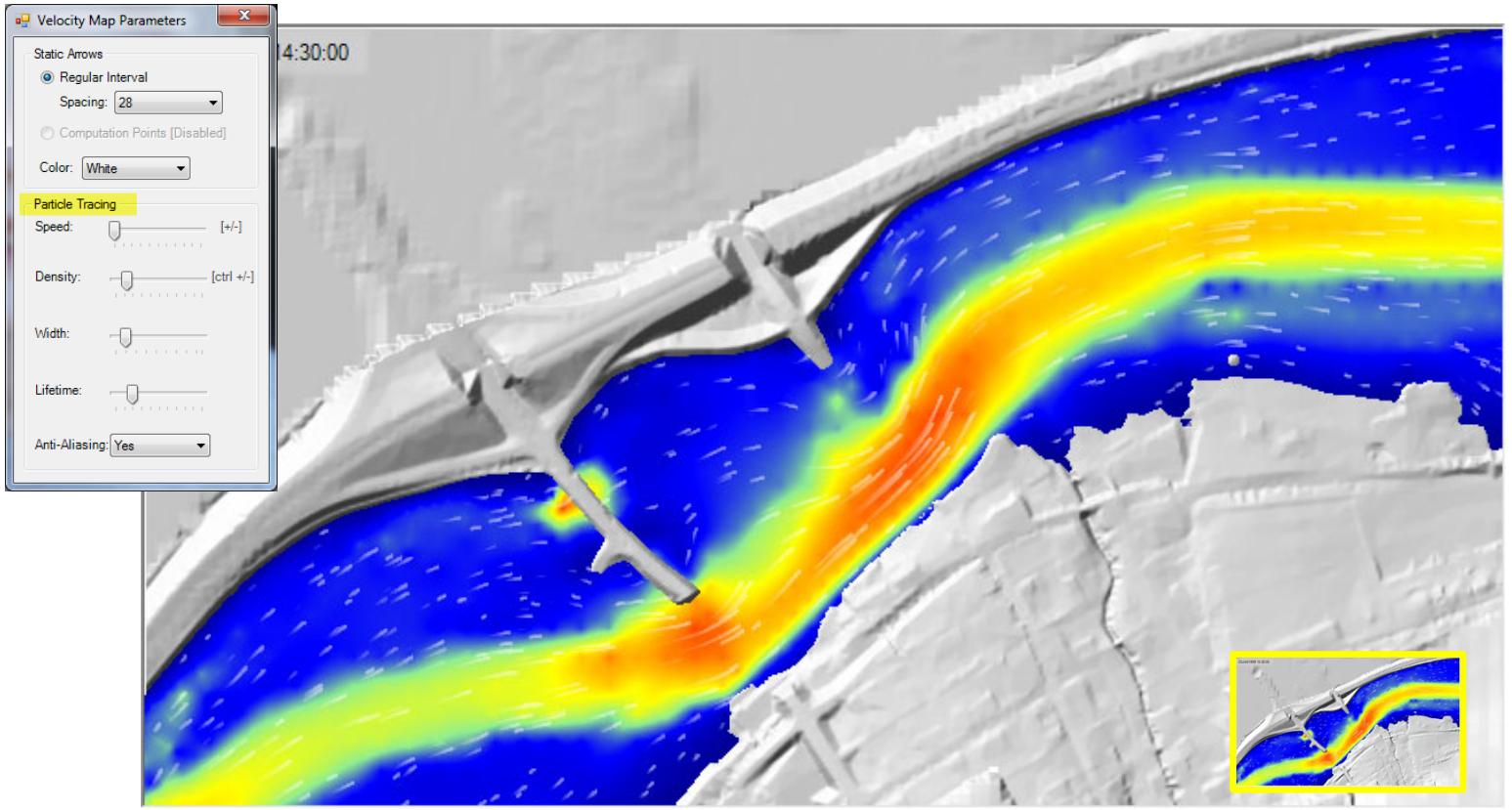
Velocity Results



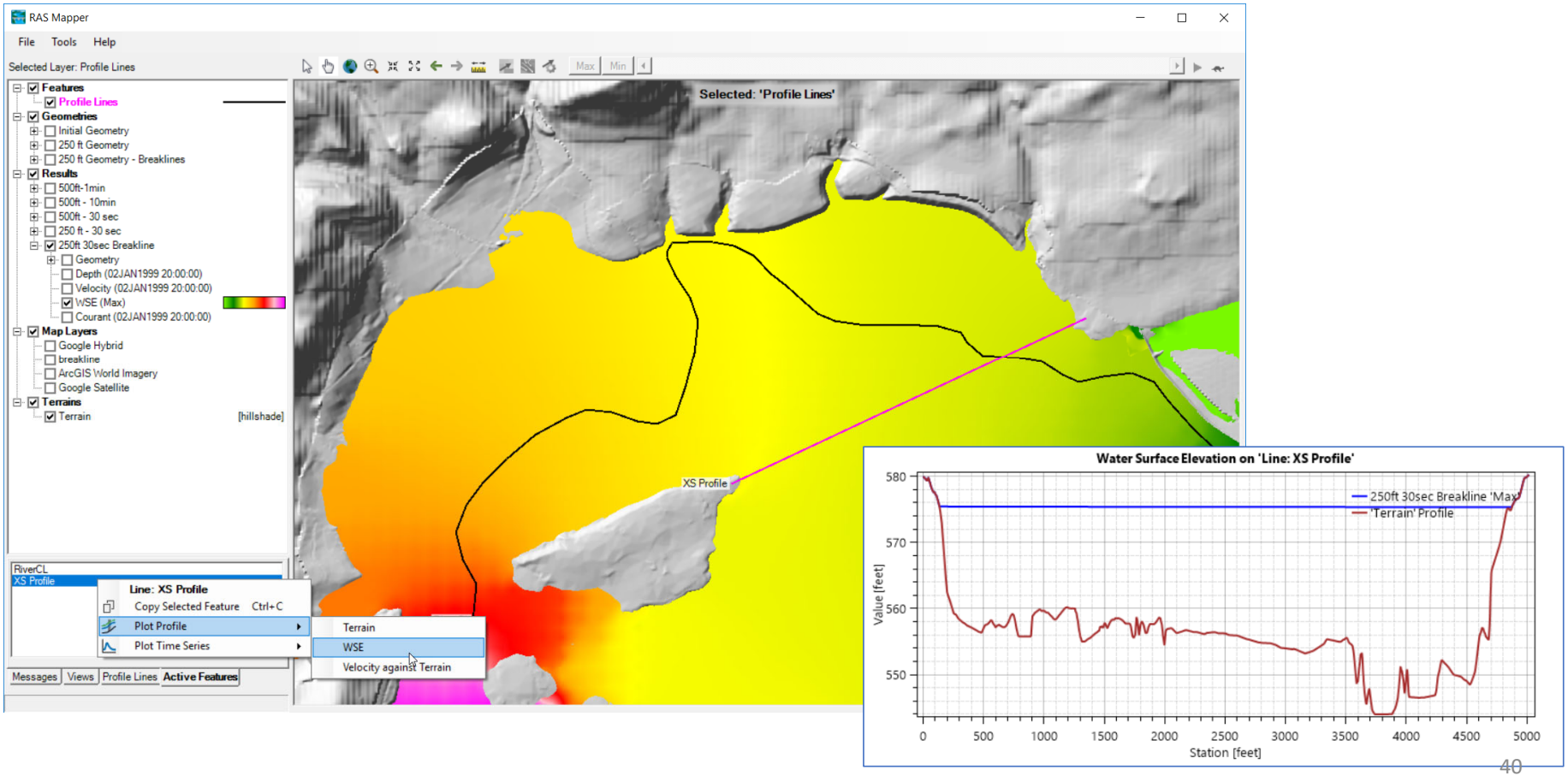
Velocity Arrows



Velocity Tracing

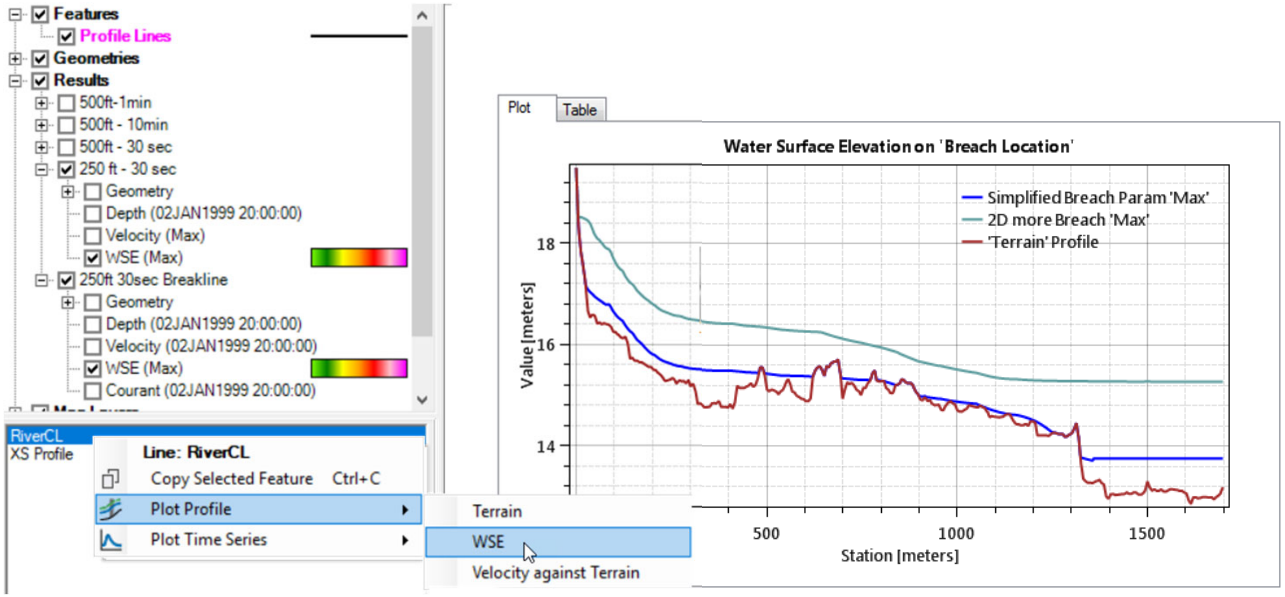


Profile Lines

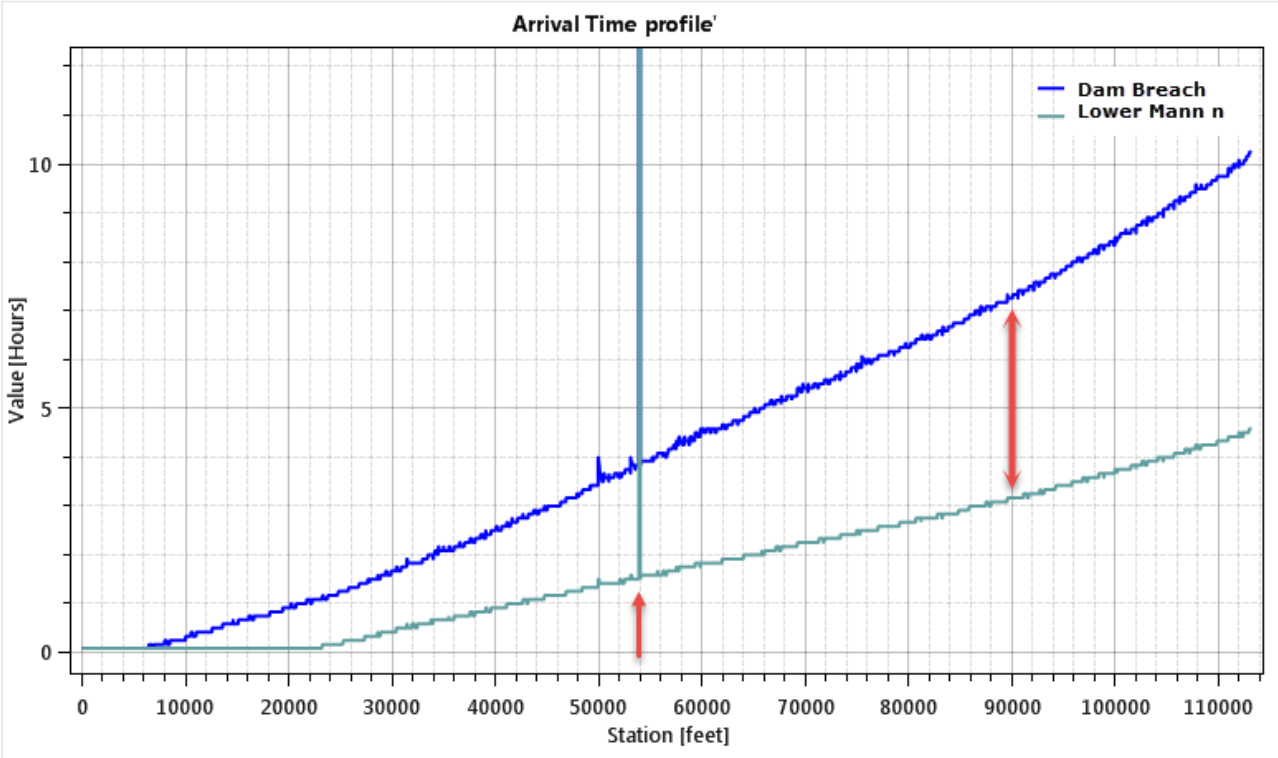


Profile Line - Comparison

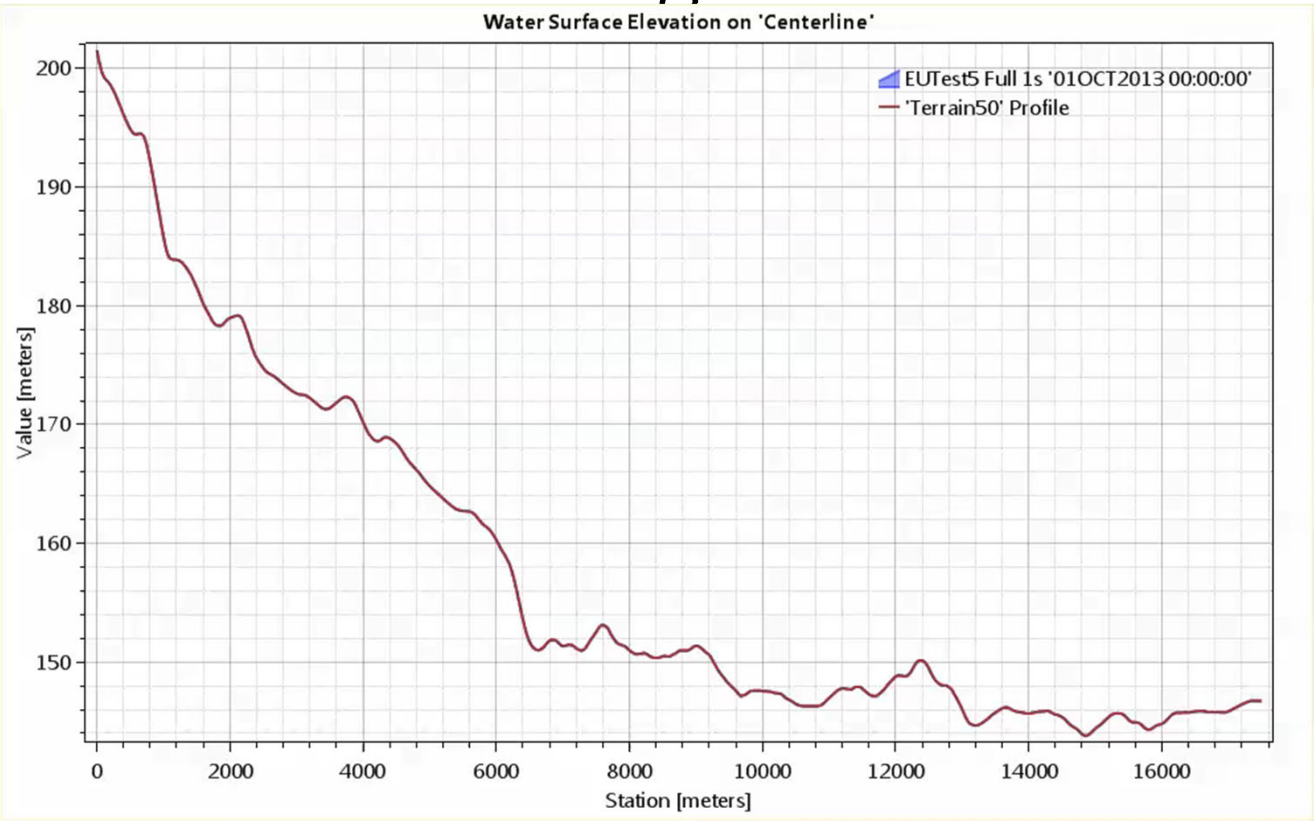
- Turn on multiple result maps
- Choose a Profile (i.e. ‘Max’)
- Choose **Plot Time Series** or **Plot Profile**



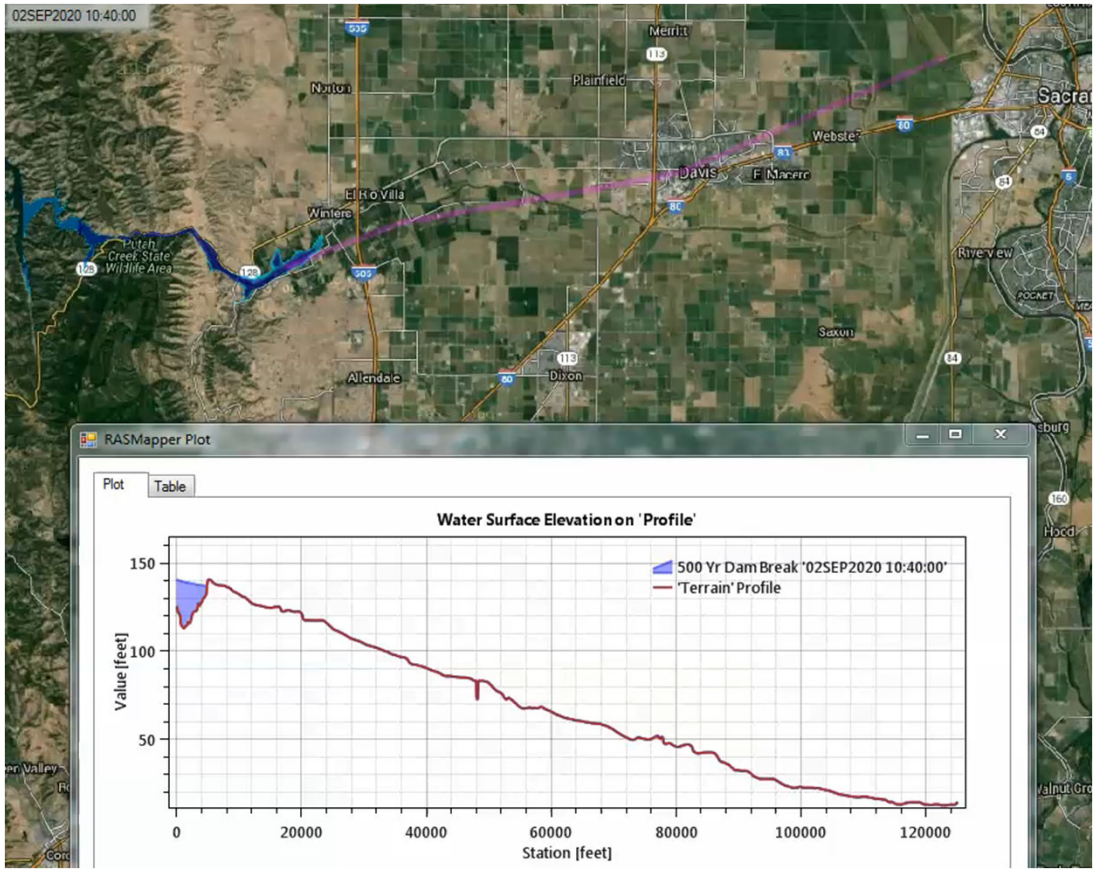
Profile Lines - Comparison



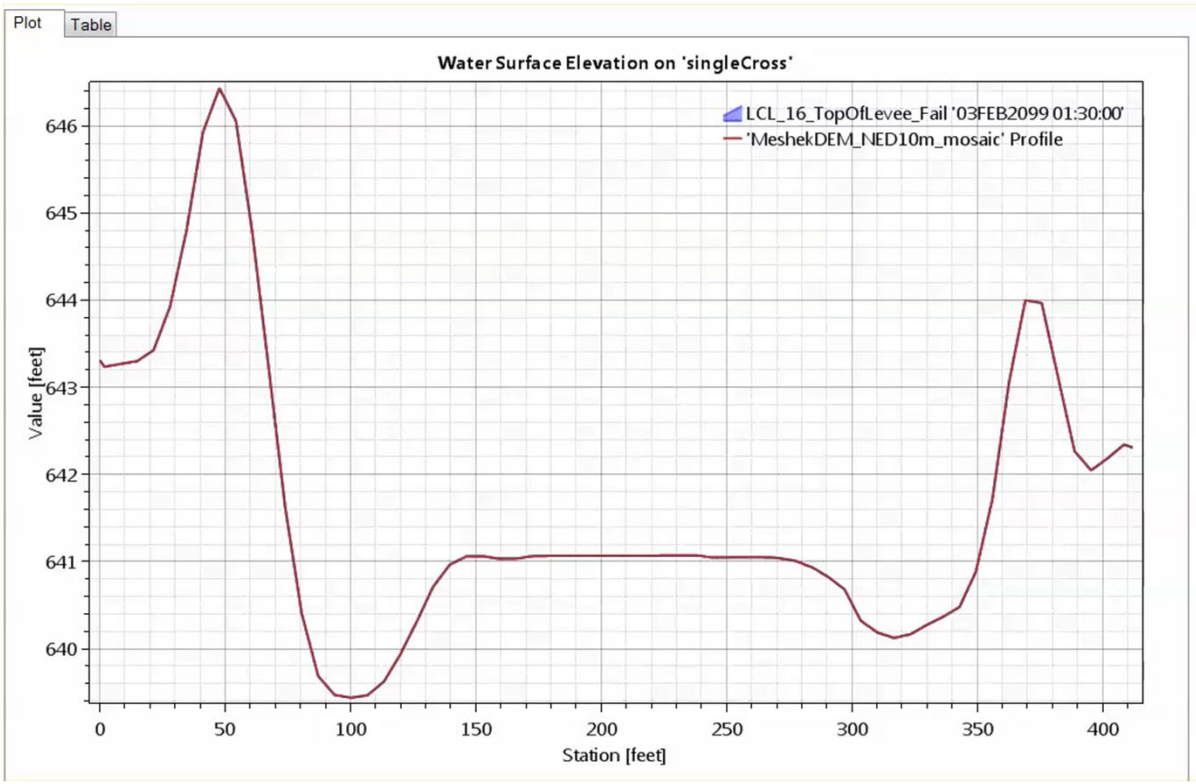
Profile Lines - Animating

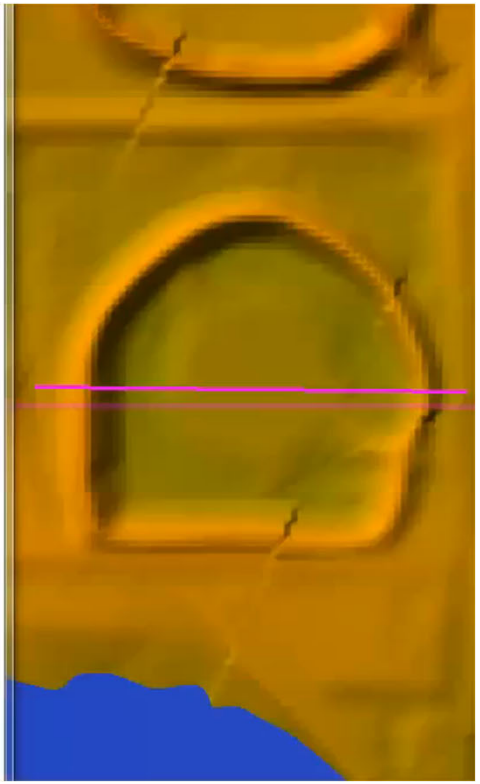


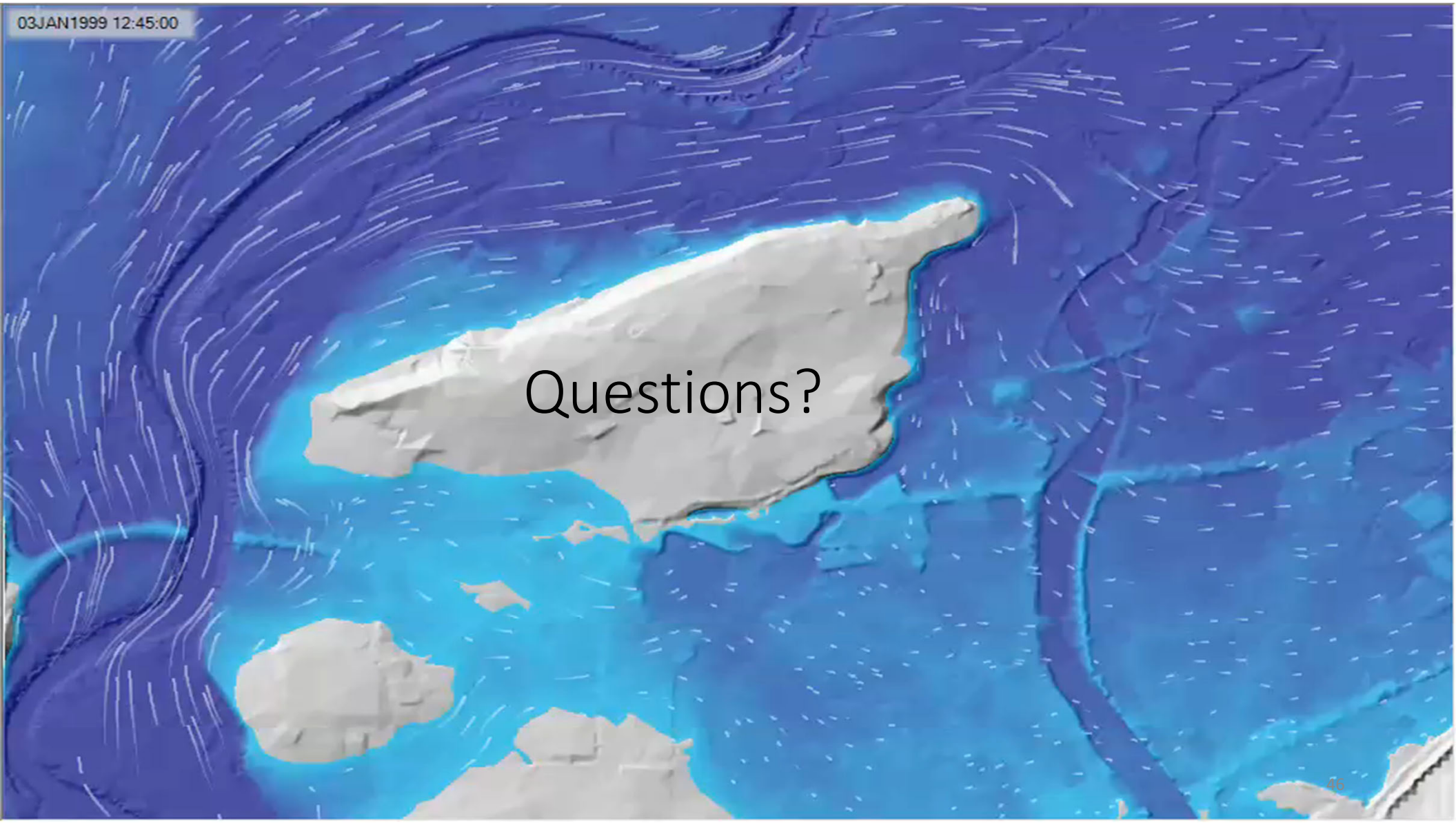
Profile Lines + Spatial Results



Profile Lines - Animating



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Questions?