

HEC-RAS 2D Sediment Workshop: Sediment Transport Equations

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Mass Conservation



- Assuming a constant water density

$$\frac{\partial h}{\partial t} + \nabla \cdot (h\mathbf{V}) = q$$

- Integrating over a computational cell

$$\frac{\partial}{\partial t} \iiint_{\Omega} d\Omega + \iint_S (\mathbf{V} \cdot \mathbf{n}) dS = Q$$

- Finite-Volume Discretization

$$\frac{\Omega_i^{n+1} - \Omega_i^n}{\Delta t} + \sum_{k \in K(i)} (\mathbf{V}_k \cdot \mathbf{n}_{ik}) A_k = Q_i$$

h : Water depth

q : Water source/sink

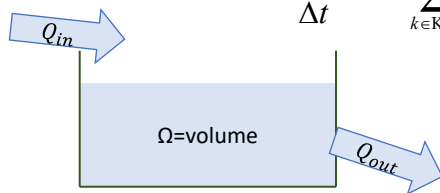
Ω_i : Cell water volume

A_k : Face area

\mathbf{V}_k : Face velocity

\mathbf{n}_{ik} : Outward face-normal unit vector


Δt : Time step




Change in volume in a
system balances with
flow through
boundaries

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Momentum Conservation



- Momentum Equation (non-conservative form)

$$\underbrace{\frac{\partial V}{\partial t}}_{\text{Temporal}} + \underbrace{(V \cdot \nabla)V}_{\text{Advection}} + \underbrace{f_c k \times V}_{\text{Coriolis}} = \underbrace{-g \nabla z_s}_{\text{Pressure gradient}} + \underbrace{\frac{1}{h} \nabla \cdot (v_t h \nabla V)}_{\text{Diffusion}} - \underbrace{\frac{\tau_b}{\rho R}}_{\text{Bottom Friction}} + \underbrace{\frac{\tau_s}{\rho h}}_{\text{Wind Stress}}$$

- From Newton's 2nd Law of motion
- Assumes constant water density, small vertical velocities, hydrostatic pressure, etc.
- Non-linear and a function of both velocity and water levels
- Continuity and Momentum Equations are the Shallow Water Equations or sometimes referred to as the "Full Momentum" equations in HEC-RAS

V : Velocity

z_s : Water level

g : Gravity

v_t : Turbulent eddy viscosity

h : Water depth

R : Hydraulic Radius


f_c : Coriolis Parameter

τ_b : Bed shear stress


τ_s : Surface stress

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Acceleration and Total Derivative



- **Eulerian:** Frame of reference fixed in space and time

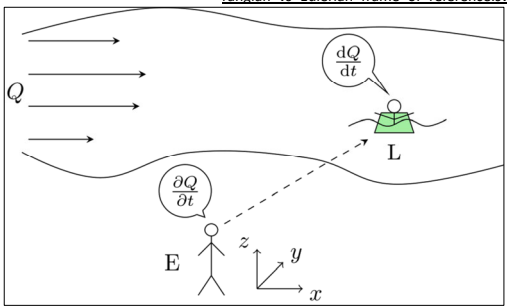
$$\frac{\partial V}{\partial t} + (V \cdot \nabla)V$$

- Easier to compute
- Time-step restricted by Courant condition

- **Lagrangian:** Frame of reference moves with total derivative along flow path

$$\frac{\partial V}{\partial t} + (V \cdot \nabla)V = \frac{DV}{Dt} = \frac{V^{n+1} - V^n}{\Delta t}$$

- More expensive to compute
- Allows larger time-steps



Velocity (V^n) at time t flow path Velocity (V^{n+1}) at time t+Δt

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Diffusion of Momentum

- Non-conservative Formulation
 - Only option in Version 5.0.7 and earlier,
 - Optional in Version 6.0

$$\frac{DV}{Dt} = -g\nabla z_s + v_t \Delta V - \frac{\tau_b}{\rho R}$$

$\Delta = \nabla^2$: Laplacian

u_N : Face-normal velocity

v_t : Turbulent eddy viscosity

h : Water depth

c_f : Non-linear friction coefficient

- Conservative Formulation
 - Default in Version 6.0
 - Only option for Eulerian SWE solver

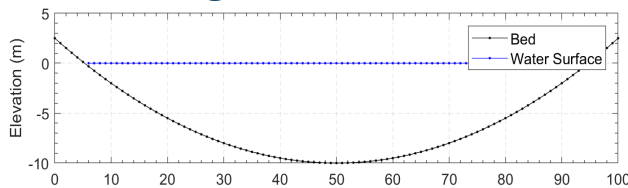
$$\frac{DV}{Dt} = -g\nabla z_s + \frac{1}{h} \nabla \cdot (v_t h \nabla V) - \frac{\tau_b}{\rho R}$$

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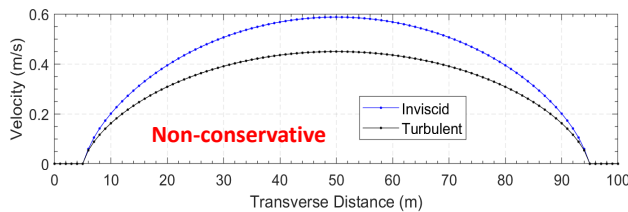
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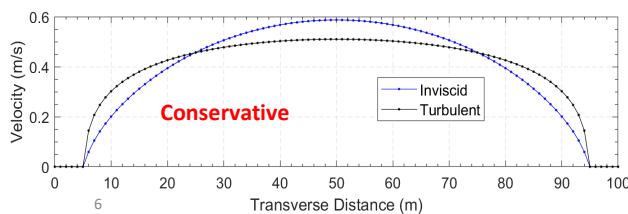
Mixing Term Formulation Comparison



Bathymetry and water level



Produces a net dissipation



Decreases velocities in middle of channel but increases velocities near banks

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Eddy Viscosity: Turbulence Model



- Old: Parabolic $\nu_t = Du_*h$
 - Versions 5.0.7 and earlier
 - Isotropic (same in all directions)
 - 1 parameter: mixing coefficient D
- New: Parabolic-Smagorinsky

$$\nu_t = \mathbf{D}u_*h + (C_s\Delta)^2 |\bar{S}|$$

$$|\bar{S}| = \sqrt{2\left(\frac{\partial u}{\partial x}\right)^2 + 2\left(\frac{\partial v}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right)^2} \quad \mathbf{D} = \begin{bmatrix} D_{xx} & 0 \\ 0 & D_{yy} \end{bmatrix} \quad \begin{aligned} D_{xx} &= D_L \cos^2 \theta + D_T \sin^2 \theta \\ D_{yy} &= D_L \sin^2 \theta + D_T \cos^2 \theta \end{aligned}$$

- Default method in Version 6.0
- Non-Isotropic (not the same in all directions)
- 3 parameters: D_L , D_T , and C_s

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Bottom Friction



- Resisting force due to relative motion of fluid against the bed
- Bed Shear Stress

$$\tau_b = \rho C_D |\mathbf{V}| \mathbf{V}$$

- Drag Coefficient

$$C_D = \frac{gn^2}{R^{1/3}}$$

- Friction coefficient

$$c_f = \frac{C_D}{R} |\mathbf{V}| = \frac{gn^2}{R^{4/3}} |\mathbf{V}|$$

n :Manning coefficient
 ρ : water density
 g : gravity acceleration constant
 $|\mathbf{V}|$: velocity magnitude
 R : hydraulic radius

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Diffusive-Wave Approximation



- Ignoring the following terms

$$\underbrace{\frac{\partial \mathbf{V}}{\partial t}}_{\text{Temporal}} + \underbrace{(\mathbf{V} \cdot \nabla) \mathbf{V}}_{\text{Advection}} + \underbrace{f \mathbf{k} \times \mathbf{V}}_{\text{Coriolis}} = - \underbrace{g \nabla z_s}_{\text{Pressure gradient}} + \underbrace{\frac{1}{h} \nabla \cdot (\mathbf{v}_t h \nabla \mathbf{V})}_{\text{Diffusion}} - \underbrace{\frac{\tau_b}{\rho R}}_{\text{Bottom Friction}} + \underbrace{\frac{\tau}{\rho h}}_{\text{Wind Stress}}$$

- Expanding and dividing both sides by the square of its norm leads to

$$\mathbf{V} = -\frac{\beta}{h} \nabla z_s \quad \beta = \frac{R^{2/3} h}{n |\nabla z_s|^{1/2}}$$

- Inserting the above equation into the Continuity Equation leads to the Diffusion-Wave Equation (DWE)

$$\frac{\partial h}{\partial t} = \nabla \cdot (\beta \nabla z_s) + q$$

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SWE vs. DWE



- Use SWE for:
 - Flows with dynamic changes in acceleration
 - Studies with important wave effects, tidal flows
 - Detail solution of flows around obstacles, bridges or bends
 - Simulations influenced by Coriolis, mixing, or wind
 - To obtain high-resolution and detailed flows
- Use DWE for:
 - Flow is mainly driven by gravity and friction
 - Fluid acceleration is monotonic and smooth, no waves
 - To compute approximate global estimates such as flood extent
 - To assess approximate effects of dam breaks
 - To assess interior areas due to levee breaches
 - For quick estimations or preliminary runs

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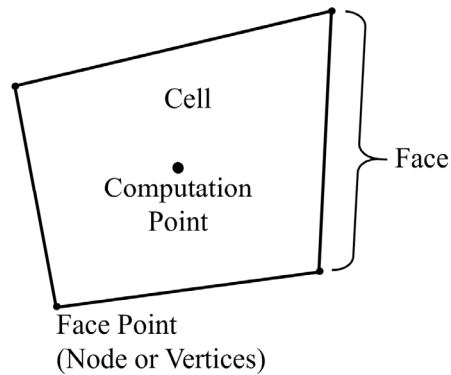
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Computational Mesh



- Mesh/grid can be unstructured
- Polygonal cells of up to 8 sides
- Cells must be concave
- Multiple 2D mesh can be run together or independently
- Grid Notation
 - Cells, Faces, Face Points (i.e. nodes or vertices), Computational Points, etc.
- State Variables
 - Cell Water levels
 - Face-normal Velocities



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Numerical Methods



- Both DWE and SWE solvers are **Semi-implicit**
- Terms treated as:
 - Explicit: acceleration and diffusion terms
 - Semi-implicit: friction, flow divergence terms, and water level gradient
 - Fully-Implicit: pressure gradient term (for $\theta = 1$)
- By treating the “fast” pressure gradient term implicitly, the time step limitation based on the wave celerity can be removed
- Both DWE and SWE use **Finite-Difference** and **Finite-Volume** Methods
- Time integration: **Finite-Difference**
- Continuity Equation: **Finite-Volume**
- Momentum Equation: **Finite-Difference** (no control volume)

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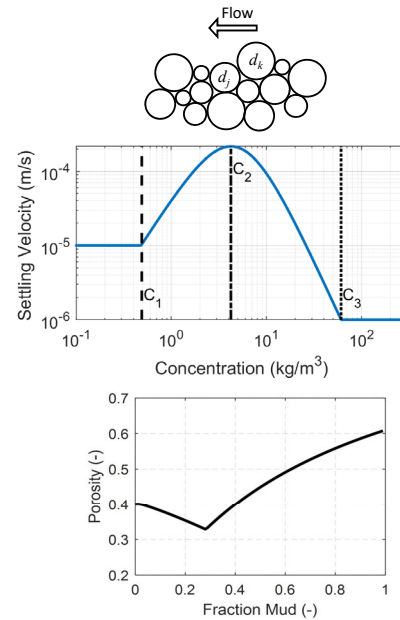


HEC-RAS 2D Sediment



• Key Features

- Mixed cohesive and non-cohesive
- Variable particle and bed bulk density
- Quasi-3D effects
- Hiding and exposure corrections
- Bed-slope effects
- Bed roughness predictors
- Packing model for bed porosity
- Avalanching
- Hindered settling
- Flocculation $f(C,T)$
- Consolidation
- Vertically varying cohesive properties
- Sheet and splash erosion
- Morphologic Acceleration
- **Subgrid bathymetry, bed sorting, erosion, deposition, and hydrodynamics**

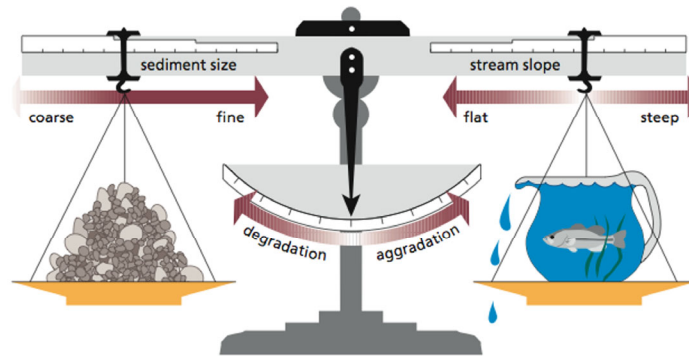


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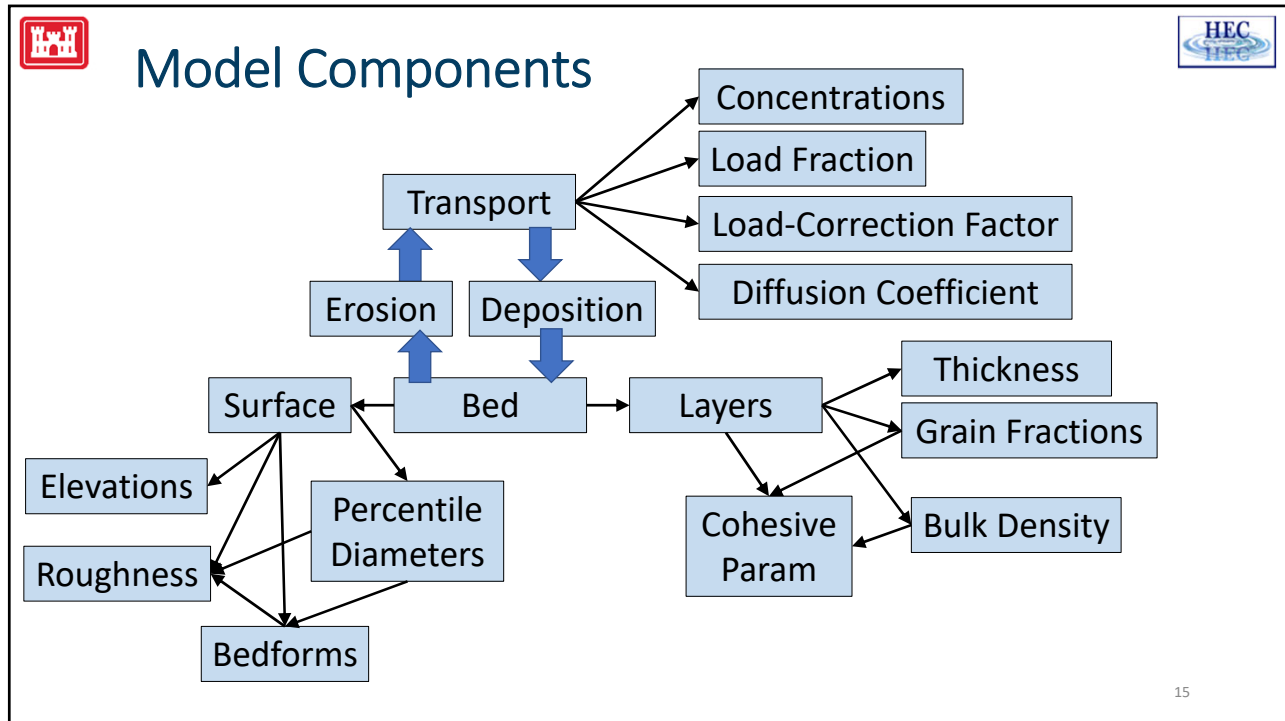
Lane's Sediment Balance



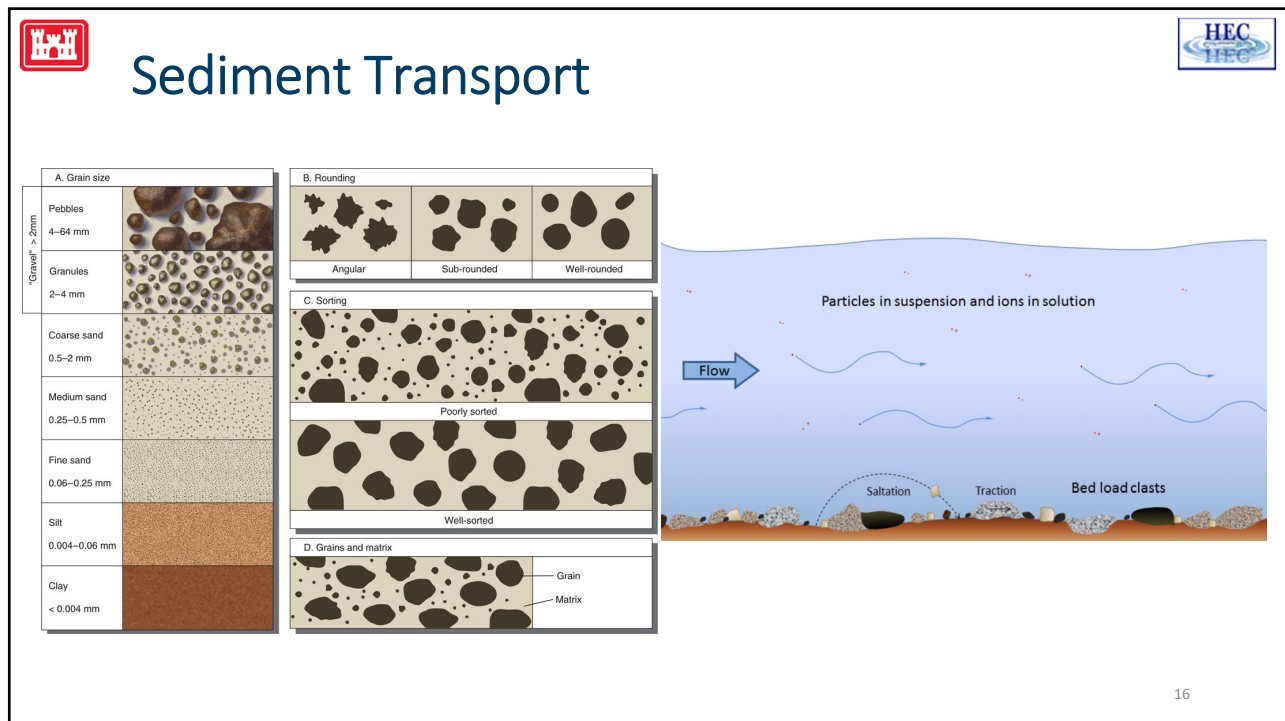
$$Q_s D_{50} \propto Q_w S$$

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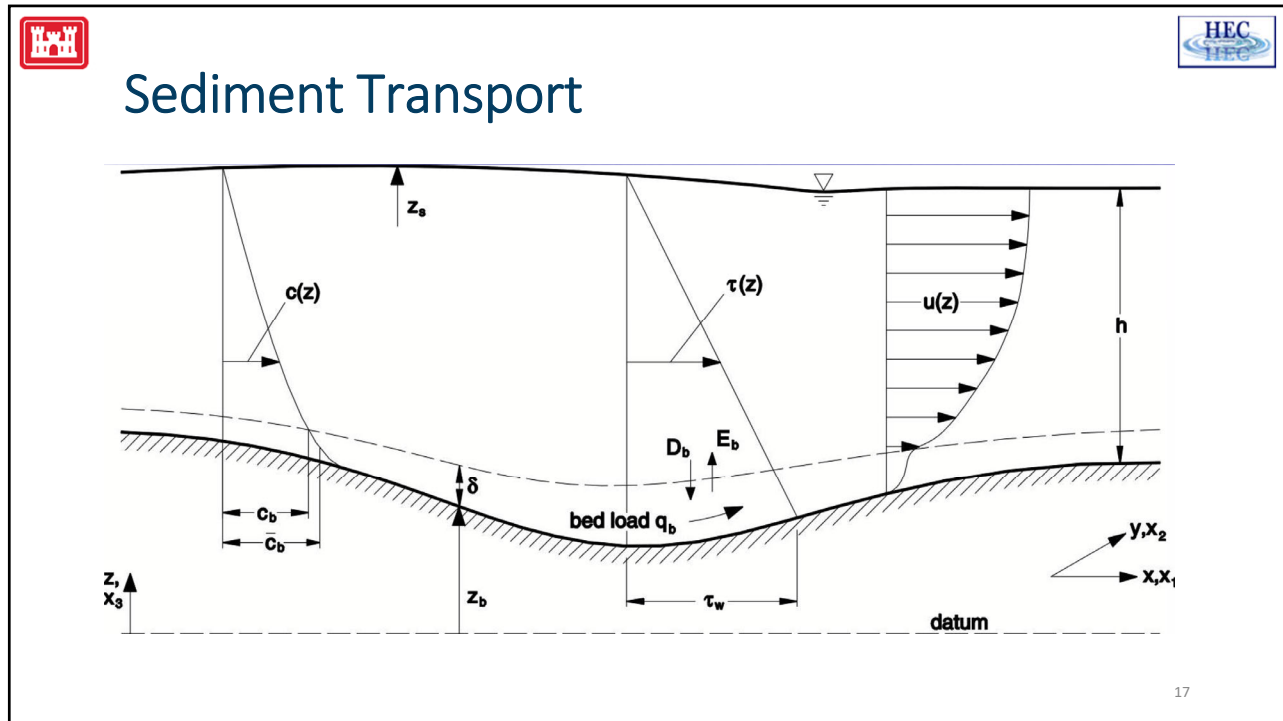
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Grain Classes

Class	Label	Min	Max	Mean	SG	n	UW	Coh?	De
1	Clay	0.002	0.004	0.003	2.65	0.82	30	1	1
2	VPM	0.004	0.008	0.006	2.65	0.61	65	1	1
3	M	0.008	0.016	0.011	2.65	0.61	65	1	1
4	MM	0.016	0.032	0.023	2.65	0.61	65	1	1
5	CM	0.032	0.0625	0.045	2.65	0.61	65	1	1
6	VFS	0.0625	0.125	0.088	2.65	0.44	93	0	1
7	FS	0.125	0.25	0.177	2.65	0.44	93	0	0.4
8	MS	0.25	0.5	0.354	2.65	0.44	93	0	0.09
9	CS	0.5	1	0.707	2.65	0.44	93	0	0.09
10	VCS	1	2	1.41	2.65	0.44	93	0	0.09
11	VPS	2	4	2.83	2.65	0.44	93	0	0.09
12	FG	4	8	5.66	2.65	0.44	93	0	0.09
13	MG	8	16	11.3	2.65	0.44	93	0	0.09
14	CG	16	32	22.6	2.65	0.44	93	0	0.09
15	VGS	32	64	45.3	2.65	0.44	93	0	0.09
16	SC	64	128	90.5	2.65	0.44	93	0	0.09
17	LC	128	256	181	2.65	0.44	93	0	0.09
18	SB	256	512	362	2.65	0.44	93	0	0.09
19	MB	512	1024	724	2.65	0.44	93	0	0.09
20	LB	1024	2048	1448	2.65	0.44	93	0	0.09

Bimodal

Percent retained vs Diameter (mm)

- Select grain classes carefully and only use them when necessary
 - Do not add a grain class which represents 0.1% of the bed material
 - Each grain class adds a transport equation, bed change, and sorting equation
- Active grain classes detected from initial bed gradations and boundary conditions

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Concentration Definition



- **Depth-averaged**

$$\hat{C}_{tk} = \frac{1}{h} \int_0^h c_{tk} dz \quad q_{tk} = \beta_t U h \hat{C}_{tk} \quad \beta_t = \frac{1}{U h \hat{C}_{tk}} \int_0^h u c_{tk} dz$$

- Coefficient for transport (advection term)
- **Used in HEC-RAS 1D**

- **Velocity weighted** (Einstein definition)

$$C_{tk} = \frac{1}{U h} \int_0^h u c_{tk} dz \quad q_{tk} = U h C_{tk}$$

- Simpler formula for transport (advection term)
- **Used in HEC-RAS 2D**
- Coefficient in temporal term

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Total-load Transport Equation



- Unsteady Advection-Diffusion Coefficient

$$\underbrace{\frac{\partial}{\partial t} \left(\frac{h C_{tk}}{\beta_{tk}} \right)}_{\text{Temporal or Storage}} + \underbrace{\nabla \cdot (h U C_{tk})}_{\text{Advection}} = \underbrace{\nabla \cdot (\epsilon_{tk} h \nabla C_{tk})}_{\text{Diffusion}} + \underbrace{E_{tk}}_{\text{Erosion}} - \underbrace{D_{tk}}_{\text{Deposition}}$$

- Simulating total-load instead of separate bed- and suspended-loads reduces computational costs because it requires half as many transport equations

k : Grain class

h : Water depth

C_{tk} : Total-load concentration

β_{tk} : Total-load correction factor

U : Current velocity

ϵ_{tk} : Total-load diffusion coefficient

E_{tk} : Total-load erosion rate

D_{tk} : Total-load deposition rate

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Erosion Rates



- Potential Erosion Rates

$$E_{tk}^* = \phi^D E_{tk}^{*SS} + \phi^W E_{tk}^{*HF}$$

- Actual Erosion Rates

$$E_{tk} = f_{1k} E_{tk}^*$$

E_{tk} → Total-load erosion rate

HF → Hydraulic flow

SS → Splash and sheet flow

ϕ^{SS} → Fraction of area with SS erosion

ϕ^{HF} → Fraction of area with CF erosion

E_{tk}^{CF} → Total-load CF erosion rate

E_{tk}^{SS} → Total-load SS erosion rate

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Bed Change



- Fractional Bed Change

$$\underbrace{\rho_{sk} (1 - \phi_b)}_{\text{Bed change}} \frac{\partial z_{bk}}{\partial t} = \underbrace{D_{tk}}_{\text{Deposition}} - \underbrace{E_{tk}}_{\text{Erosion}} + \underbrace{\nabla \cdot (\kappa_{bk} |q_{bk}| \nabla z_b)}_{\text{Bed slope term}}$$

- Total Bed Change

$$\frac{\partial z_b}{\partial t} = \sum_k \frac{\partial z_{bk}}{\partial t}$$

z_b : Bed elevation [L]

ρ_{sk} : Grain density [M/L³]

ϕ_b : Bed Porosity [-]

D_{tk} : Fractional deposition rate [M/L²/T]

E_{tk} : Fractional erosion rate [M/L²/T]

κ_{bk} : Bedslope coefficient [-]

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Bed Layering

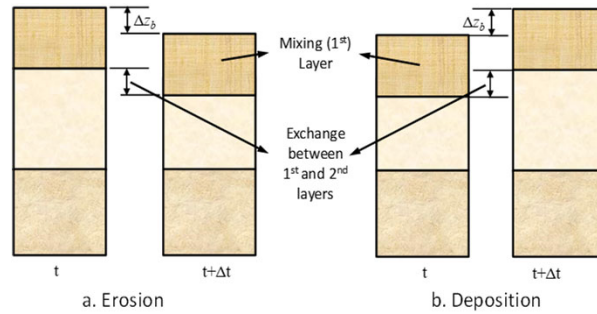
- Active Layer

$$\delta_1 = \max(f_{1,90}d_{90}, 0.5\Delta)$$

Δ : Bedform height

- Second Layer

$$\frac{\partial \delta_2}{\partial t} = \frac{\partial z_b}{\partial t} - \frac{\partial \delta_1}{\partial t}$$



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Bed Sorting Model: Variable Bulk Density

- Bed Mass Concentrations

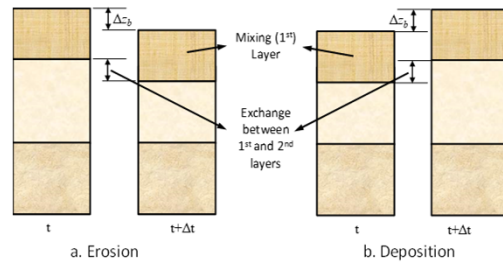
$$\frac{\partial(m_{1k}\delta_1)}{\partial t} + m_{*k} \frac{\partial \delta_2}{\partial t} = \rho_{sk}(1-\phi_b) \frac{\partial z_{bk}}{\partial t} \quad \frac{\partial(m_{2k}\delta_2)}{\partial t} = m_{*k} \frac{\partial \delta_2}{\partial t} \quad m_{*k} = \begin{cases} m_{1k} & \text{for } \frac{\partial \delta_2}{\partial t} \geq 0 \\ m_{2k} & \text{otherwise} \end{cases}$$

- Dry Bulk Density and Mass Fractions

$$\rho_{d1} = \sum_k m_{1k} \quad f_{1k} = \frac{m_{1k}}{\rho_{d1}}$$

- Advantages

- Efficient
- Preserves layer boundaries
- Consistent



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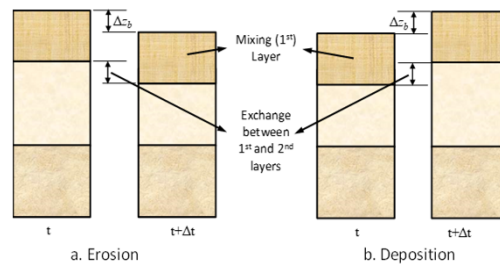
Bed Sorting Model: Constant Bulk Density

- Grain Fractions (by mass)

$$\frac{\partial(f_{1k}\delta_1)}{\partial t} + f_{*k} \frac{\partial\delta_2}{\partial t} = \frac{\partial z_{bk}}{\partial t} \quad \frac{\partial(f_{2k}\delta_2)}{\partial t} = f_{*k} \frac{\partial\delta_2}{\partial t} \quad f_{*k} = \begin{cases} f_{1k} & \text{for } \frac{\partial\delta_2}{\partial t} \geq 0 \\ f_{2k} & \text{otherwise} \end{cases}$$

- Advantages

- Most efficient
- Preserves layer boundaries
- Consistent



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Bed Sorting Model

- Model used automatically selected by engine based on the input
- Constant input bulk densities
 - Constant Bulk Density Model
- Variable input bulk densities or cohesives
 - Variable Bulk Density Model
- Constant bulk density model is simpler, faster, and more stable obviously because it has few

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Fractions by Weight and Volume

- Fractions by weight/mass

$$m_k = f_k M \quad M = \sum_k m_k$$

- Fractions by volume

$$v_k = \hat{f}_k V \quad V = \sum_k v_k$$

- Conversion

$$m_k = \rho_{sk} v_k \quad f_k = \frac{\rho_{sk} \hat{f}_k}{\sum_i \rho_{si} \hat{f}_i} \quad \hat{f}_k = \frac{\rho_{sk}^{-1} f_k}{\sum_i \rho_{si}^{-1} f_i}$$

- Dry bulk density

$$\rho_d = (1-\phi) \sum_k \hat{f}_k \rho_{sk} = (1-\phi) \left(\sum_k \rho_{sk}^{-1} f_k \right)^{-1}$$

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Bed Porosity (Newly Deposited Material)

- Noncohesives

$$\frac{\hat{f}_n}{1-\phi_n} = \sum_k \frac{\hat{f}_k}{1-\phi_k} \text{ for } k \in \text{noncohesive}$$

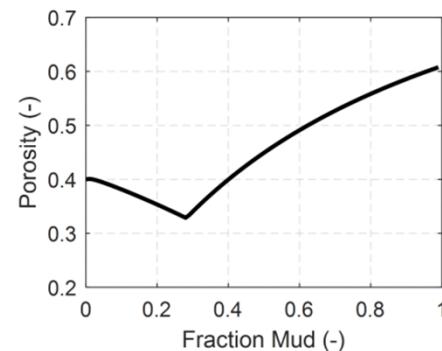
- Cohesives

$$\frac{\hat{f}_c}{1-\phi_c} = \sum_k \frac{\hat{f}_k}{1-\phi_k} \text{ for } k \in \text{noncohesive}$$

- Bimodal Mixture

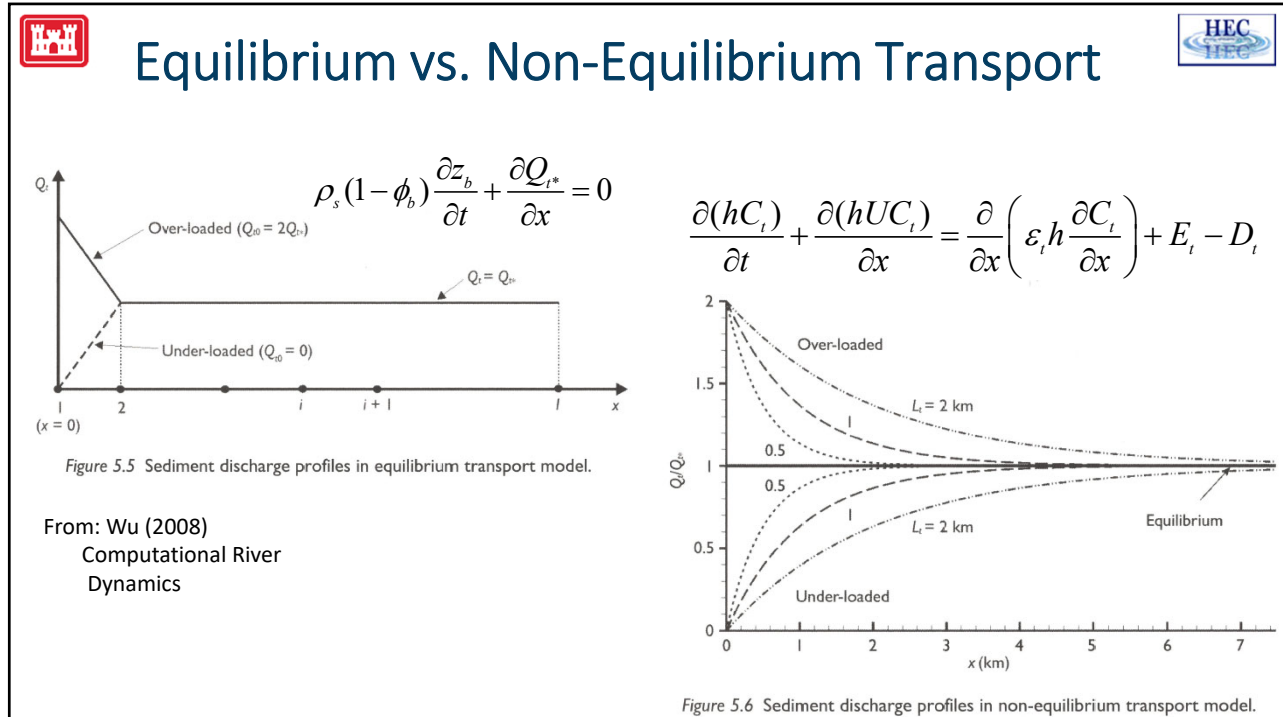
$$\frac{1}{1-\phi_b} = (1-B) \frac{\hat{f}_n}{1-\phi_n} + \hat{f}_n B + \frac{\hat{f}_c}{1-\phi_c}$$

B : Packing parameter




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Deriving Exner



- Starting with the transport and bed change equations and ignoring terms

$$\cancel{\frac{\partial(hC_t)}{\partial t}} + \frac{\partial(hUC_t)}{\partial x} = \cancel{\frac{\partial}{\partial x} \left(\epsilon_t h \frac{\partial C_t}{\partial x} \right)} + E_t - D_t$$

$$\rho_s(1-\phi_b)\frac{\partial z_b}{\partial t} = D_t - E_t$$

- Assuming the concentration is at equilibrium and defining the transport rate

$$C_t = C_{t^*} = \frac{Q_{t^*}}{hU}$$

- Combining the equations leads to the Exner equation

$$\rho_s(1-\phi_b)\frac{\partial z_b}{\partial t} + \frac{\partial Q_{t^*}}{\partial x} = 0$$

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Equilibrium vs. Non-Equilibrium Transport



Equilibrium

- Pros
 - ▶ Simpler
 - ▶ Computationally efficient
 - ▶ Less parameters
 - ▶ Works well for large-scale models
- Cons
 - ▶ Less realistic
 - ▶ Breaks down for high-resolution models

Non-Equilibrium

- Pros
 - ▶ Physically-based
 - ▶ Works for all scales
- Cons
 - ▶ Computationally expensive
 - ▶ More parameters to calibrate

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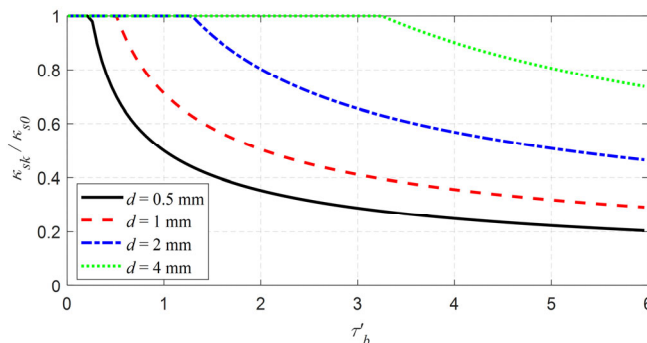
Bed Slope Coefficient



- Accounts for down-slope movement of sediment during transport
- Larger grains more influenced by bed-slope
- Bed-slope effect less with increasing transport
- Tends to smooth bed elevations and thereby improve stability

$$\kappa_{bk} = \kappa_{b0} \sqrt{\frac{\tau_{crk0}}{\max(\tau'_b, \tau_{crk0})}}$$

$$\kappa_{b0} \approx 0.1 - 0.5$$



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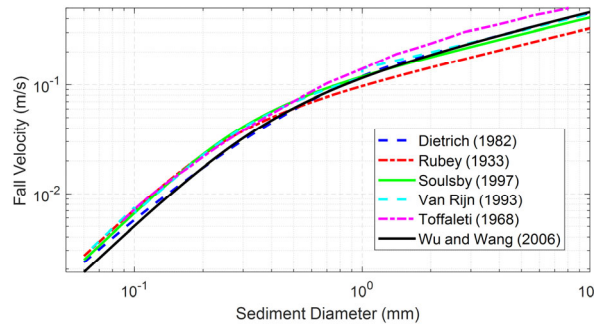
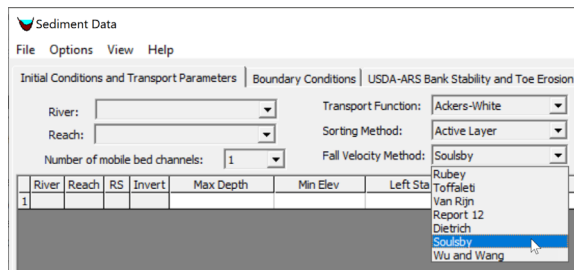
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Fall Velocity



- Represents free settling velocity
 - Does not account for hindered settling or flocculation
- Not a calibration parameter
- Use Soulsby except for specific conditions



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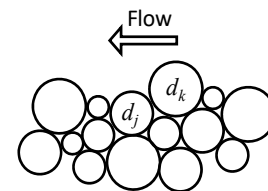
Hiding and Exposure



- Smaller particles “hidden” from flow and larger particles “exposed” to flow
- Hiding and exposure corrections
 - Incipient motion/mobility

$$\xi_k = \frac{\theta_{crk}}{\theta_{cr}} = \frac{\tau_{crk}}{\tau_{cr}} = \frac{U_{crk}^2}{U_{cr}^2}$$

• Transport $\eta_k = \frac{q_k^*}{q^*}$ $\eta_k \approx \frac{1}{\xi_k^a}$ a : Coefficient



- Correction on incipient motion done whenever possible unless formula does not have a threshold for incipient motion
- Because finer grain sizes represent a larger portion of the transported material, **applying** hiding/exposure corrections will generally **reduce** the overall transport
- **ALWAYS** use hiding and exposure corrections (default is off)

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Hiding and Exposure Functions



- None (default) – Not recommended
- Ashida and Michiue (1971)

$$\xi_k = \begin{cases} \left[\frac{\log_{10}(19)}{\log_{10}(19d_k / d_m)} \right]^2 & \text{for } d_k / d_m \geq 0.4 \\ d_m / d_k & \text{for } d_k / d_m < 0.4 \end{cases}$$

- Day (1980)
 - Developed for Ackers and White formula

$$\eta_k = \frac{1}{0.4(d_k / d_A)^{-0.5} + 0.6}$$

$$d_A = 1.6d_{50} \left(\frac{d_{84}}{d_{16}} \right)^{-0.28}$$

- Egiazaroff (1965)

► Used in AdH

$$\xi_k = \left[\frac{\log_{10}(19)}{\log_{10}(19d_k / d_m)} \right]^2$$

- Hayashi (1980)

$$\xi_k = \begin{cases} \left[\frac{\log_{10}(8)}{\log_{10}(8d_k / d_m)} \right]^2 & \text{for } d_k / d_m \geq 1 \\ d_m / d_k & \text{for } d_k / d_m < 1 \end{cases}$$

- Parker et al. (1982)

$$\xi_k = \left(\frac{d_k}{d_{50}} \right)^{-m}$$

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Hiding and Exposure Functions



- Proffitt and Sutherland (1983)
 - Developed for Ackers and White

$$\eta_k = \begin{cases} 0.4 & \text{for } d_k / d_u \leq 0.075 \\ 0.53 \log_{10}(d_k / d_u) + 1 & \text{for } 0.075 < d_k / d_u \leq 3.7 \\ 1.3 & \text{for } d_k / d_u > 3.7 \end{cases}$$

- Wilcock and Crowe
 - Developed for Wilcock and Crowe

$$\xi_k = \frac{\tau_{r,k}}{\tau_{r,sm}} = \left(\frac{d_k}{d_{sm}} \right)^{b_k}$$

$$b_k = \frac{0.67}{1 + \exp\left(1.5 + \frac{d_k}{d_{sm}}\right)}$$

- Wu et al. (2000)

► Developed for Wu et al.

$$\xi_k = \left(\frac{P_{ek}}{P_{hk}} \right)^{-m}$$

► Most physically based

► Uses entire grain size distribution

► Hiding and exposure probabilities

$$P_{hk} = \sum_{j=1} \hat{f}_{1j} \frac{d_j}{d_k + d_j}$$

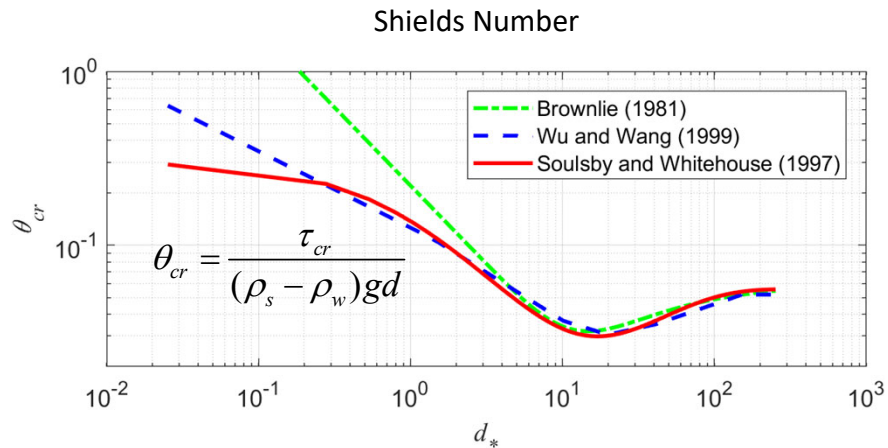
$$P_{ek} = \sum_{j=1} \hat{f}_{1j} \frac{d_k}{d_k + d_j}$$

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Critical Shear for Erosion of Noncohesives



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Critical Velocity for Erosion of Noncohesives



- Van Rijn (1984)

$$U_{cr} = \begin{cases} 0.19d_{50}^{0.1} \log_{10} \left(\frac{4h}{d_{90}} \right) & \text{for } 0.1 \leq d_{50} \leq 0.5 \text{ mm} \\ 8.5d_{50}^{0.6} \log_{10} \left(\frac{4h}{d_{90}} \right) & \text{for } 0.5 \leq d_{50} \leq 2.0 \text{ mm} \end{cases}$$

- Yang (1973)

$$\frac{U_{cr}}{\omega_{sd}} = \begin{cases} \frac{2.5}{\log_{10} \left(\frac{u_* d}{\nu} \right) - 0.06} + 0.66 & \text{for } 1.2 < \frac{u_* d}{\nu} < 70 \\ 2.05 & \text{for } \frac{u_* d}{\nu} \geq 70 \end{cases}$$

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Transport Potential Formulas



- Most important model setting by far
- Available formulas
 - Ackers and White (1973)
 - Engelund-Hansen (1967)
 - Lausen-Copeland (1989)
 - Meyer-Peter-Muller (1948)
 - Soulsby-van Rijn (1997)
 - Toffaleti (1968)
 - Van Rijn (1984ab, 2007ab)
 - Wilcock and Crowe (2003)
 - Wu et al. (2000)
 - Yang (1984)

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Transport Function



Sediment Data - Sediment Nonuniform

File Options View Help

Initial Conditions and Transport Parameters | Boundary Conditions | USDA-ARS Bank Stability and Toe Erosion Model (BSTEM) | 2D Sedime

River: Transport Function: Wu

Reach: Sorting Method: Meyer Peter Muller

Number of mobile bed channels: 1 Fall Velocity Method: Toffaleti

MPM-Toffaleti

Yang

Wilcock-Crowe

Soulsby-van Rijn

van Rijn (2007)

Wu

Define/Edit Bed Gradation ...

Define Layers...

River	Reach	RS	Invert	Max Depth	Min Elev	Left St	Bed Gradation
1							

Fall Velocity Methods:

- Ruby
- Toffaleti
- Van Rijn
- Report 12
- Dietrich
- Soulsby
- Wu and Wang

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Ackers and White (1973)



- Total-load Formula
- Excess mobility based on stream power Fractional load formulation adopted for nonuniform sediments by Day (1980) and Proffitt and Sutherland (1983) for nonuniform sediments
- Works well for nonuniform sands and gravels

$$q_{tk}^* = \rho_w g h U X_{tk}^* \quad \frac{X_{tk}^* h \rho_w}{d_k \rho_{sk}} \left(\frac{u_*}{U} \right)^n = \Lambda \left(\frac{F_{grk}}{A_c} - 1 \right)^m$$

$$F_{grk} = \eta_k \frac{u_*^n}{\sqrt{R_k g d_k}} \left[\frac{U}{\sqrt{32 \log_{10}(10h/d_k)}} \right]^{1-n}$$

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Engelund-Hansen (1967)



- Total-load Formula
- Threshold for transport
 - Originally did not use one
 - Included in HEC-RAS 2D Sediment
- Uniform sediments dominated by suspended load

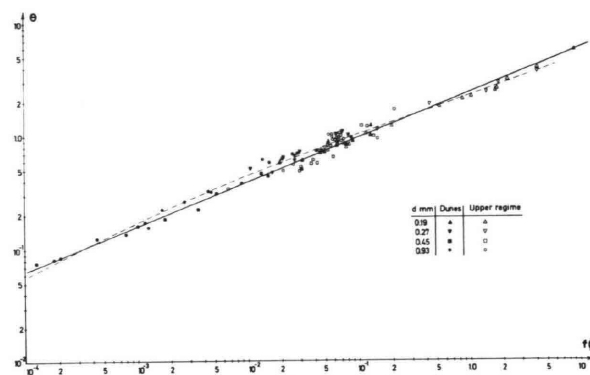


Figure 4.3.1

$$q_{tk}^* = \begin{cases} 0.05 \eta_k \rho_{sk} U^2 \sqrt{\frac{d_k}{g R_k}} \left(\frac{\tau_b}{g(\rho_{sk} - \rho_w) d_k} \right)^{3/2} & \text{for } \tau_b > \tau_{crk} \\ 0 & \text{otherwise} \end{cases}$$

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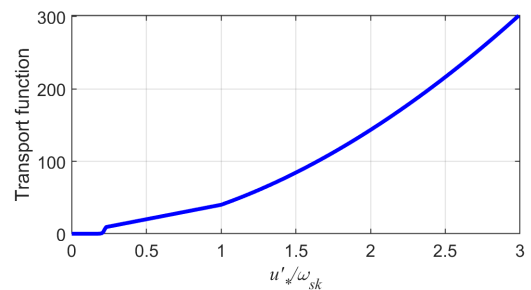


Laursen-Copeland (1968, 1989)



- Total-load Formulas (continued)
- Nonlinear excess shear formulation with empirical transport function
- Based on flume experiments and data from Arkansas River.
- Copeland extended Laursen equation to gravel

$$q_{tk}^* = a \rho_w U h \left(\frac{d_k}{h} \right)^{7/6} \left(\frac{\theta'_b}{\theta_{crk}} - 1 \right)^n f_{tk}^{LC} \left(\frac{u'_*}{\omega_{sk}} \right)$$



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Meyer-Peter-Müller (1948)



- Bed-load Formula
- Excess shear formulation
- Recalibrated several times in literature
- Most appropriate for uniform gravel
- Tends to under-predict for sands and silts

$$q_{bk}^* = A_M \rho_{sk} \sqrt{R_k g d_k^3} (\theta'_b - \theta_{crk})^{E_M}$$

$$MPM \Rightarrow A_M = 8, E_M = 2/3, \text{ and } \theta_{crk} = 0.047$$

$$\text{Wong and Parker (2006)} \Rightarrow A_M = 3.97, E_M = 1.6, \text{ and } \theta_{crk} = 0.0495$$

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Soulsby-van Rijn (1997)



- Total-load Formulas
- Developed by curve-fitting to a 2DV sediment transport model SEDTRANS by van Rijn
- Uses depth-averaged threshold current velocity
- Originally proposed for well sorted sands and extended here for nonuniformly sized sediments

$$q_{bk}^* = 0.005Uh \left(\frac{U - U_{crk}}{\sqrt{R_k g d_k}} \right)^{2.4} \left(\frac{d_k}{h} \right)^{1.2}$$

$$q_{sk}^* = 0.012Uh \left(\frac{U - U_{crk}}{\sqrt{R_k g d_k}} \right)^{2.4} \left(\frac{d_k}{h} \right) d_{*k}^{-0.6}$$

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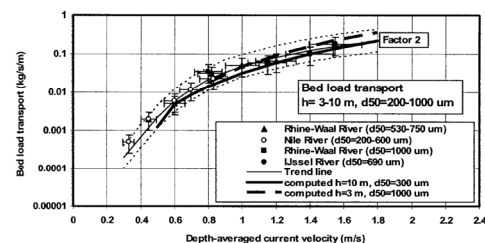
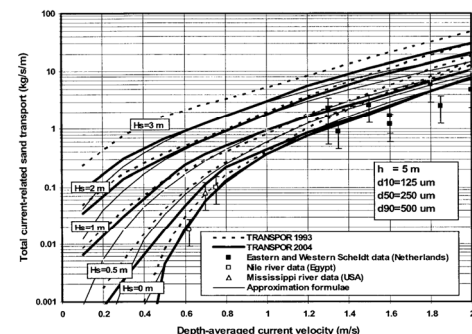
Van Rijn (1984ab, 2007ab)



- Total-load Formula
- Developed by curve-fitting to lab and field measurements
- Uses depth-averaged threshold current velocity
- Originally proposed for well sorted sands and extended here for nonuniformly sized sediments
- Suspended-load formula the same as the Soulsby-van Rijn

$$q_{bk}^* = 0.015Uh \left(\frac{U - U_{crk}}{\sqrt{R_k g d_k}} \right)^{1.5} \left(\frac{d_k}{h} \right)^{1.2}$$

$$q_{sk}^* = 0.012Uh \left(\frac{U - U_{crk}}{\sqrt{R_k g d_k}} \right)^{2.4} \left(\frac{d_k}{h} \right) d_{*k}^{-0.6}$$



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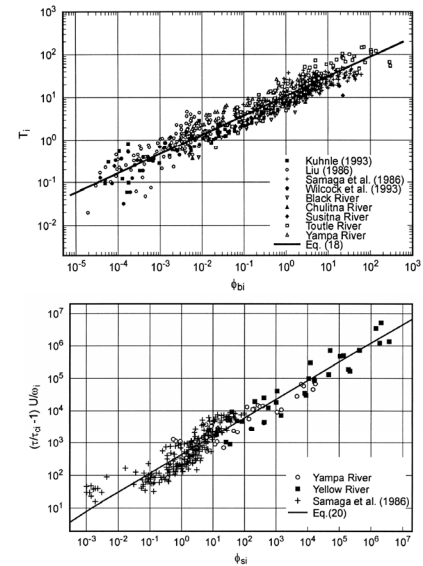


Wu et al. (2000)

- Total-load Formula
- Developed for nonuniform sediments
- Based on extensive lab and field measurements
- Nonlinear excess shear formulation for bed-load
- Stream-power formulation for suspended-load

$$q_{bk}^* = 0.0053 \sqrt{R_k g d_k^3} \left(\frac{\tau_b'}{\tau_{crk}} - 1 \right)^{2.2}$$

$$q_{sk}^* = 2.62 \times 10^{-5} \sqrt{R_k g d_k^3} \left[\left(\frac{\tau_b}{\tau_{crk}} - 1 \right) \frac{U}{\omega_{sk}} \right]^{1.74}$$



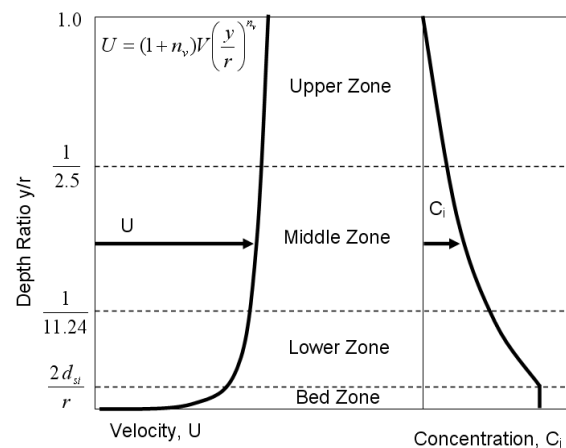
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Toffaletti (1968)

- Total-load formulas
- Developed primarily for sand
- Splits the water column into 3 zones
- Assumes Rouse concentration profile
- Originally developed for bulk transport but here it is applied to individual grain classes
- Usually applied at “large” rivers since most of the data used to develop it were from large suspended-load dominant rivers
- Bed-load formula does not perform well for gravel and can be replaced with MPM



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Wilcock and Crowe (2003)



- Bed-load Formula
- Developed for graded beds with sand and gravel
- No critical shear for transport
- However, it quickly goes to zero

$$q_{bk}^* = \frac{u_*^3 W_k^*}{R_k g}$$

$$W_k^* = \begin{cases} 0.002\phi^{7.5} & \text{for } \phi < 1.35 \\ 14 \left(1 - \frac{0.894}{\phi^{0.5}} \right)^{4.5} & \text{for } \phi \geq 1.35 \end{cases} \quad \phi = \frac{\tau_b}{\tau_{r,k}}$$

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Yang (1979, 1984)



- Total-load formula
- Regression of potential energy dissipation
- Best for fine to medium sands
- Overestimates for coarse sands and gravel
- Sharp discontinuity at diameter of 2 mm

$$\log_{10}(C_{tk}^*) = M + N \log_{10} \left[\frac{S_f}{\omega_{sk}} (U - U_{crk}) \right]$$

$$M = M \left(\frac{\omega_{sk} d_k}{\nu}, \frac{u_*}{\omega_{sk}} \right), \quad N = N \left(\frac{\omega_{sk} d_k}{\nu}, \frac{u_*}{\omega_{sk}} \right)$$

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Thank You!

HEC-RAS Website:

<https://www.hec.usace.army.mil/software/hec-ras/>

Online Documentation:

<https://www.hec.usace.army.mil/confluence/rasdocs>



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